

The Force Feedback Microscope: an AFM for soft condensed matter

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Advisors

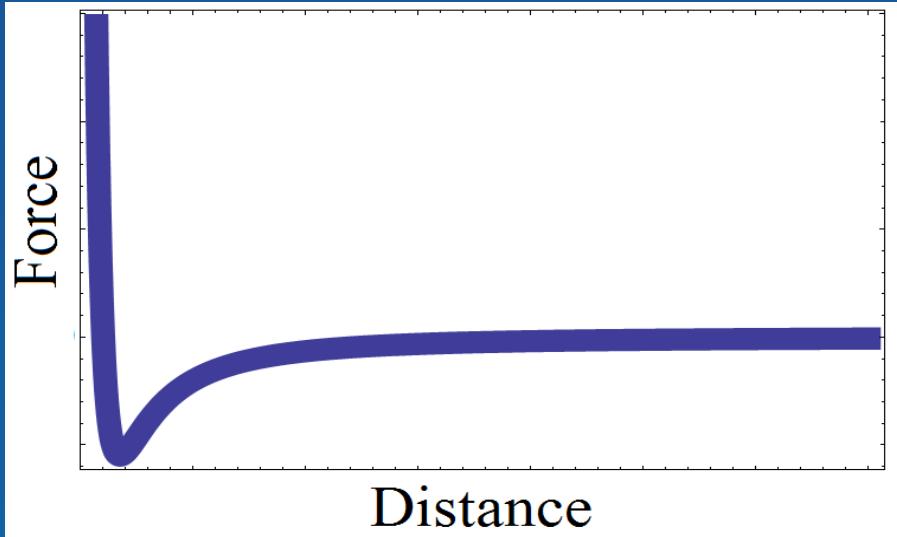
Fabio Comin – ESRF, Grenoble
Joel Chevrier – UJF, Institut Néel, Grenoble



Outline

- *Motivation*
- *The Force Feedback Microscope*
- *Results*
- *Theory*
- *Conclusions*

The interaction Force

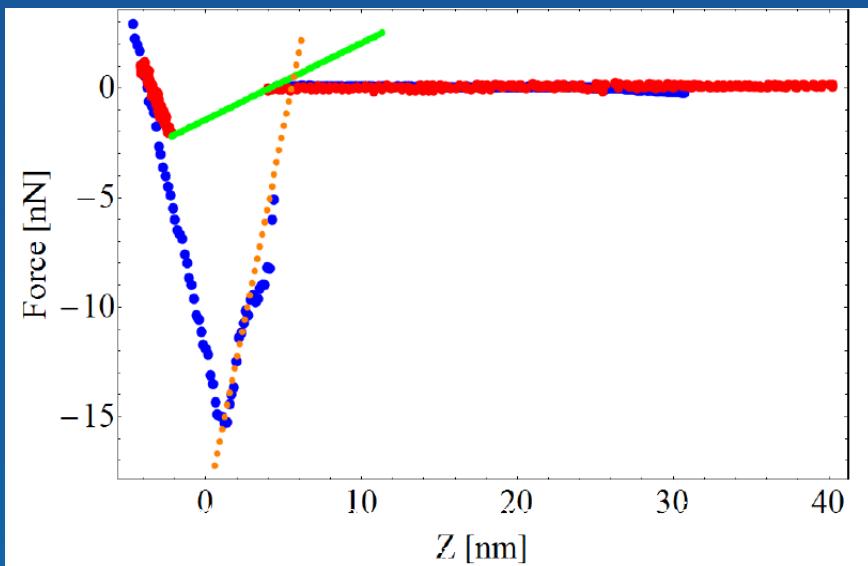


...all things are made of atoms - little particles that move around in perpetual motion, attracting each other when they are a little distance apart, but repelling upon being squeezed onto one another...

R. Feynman

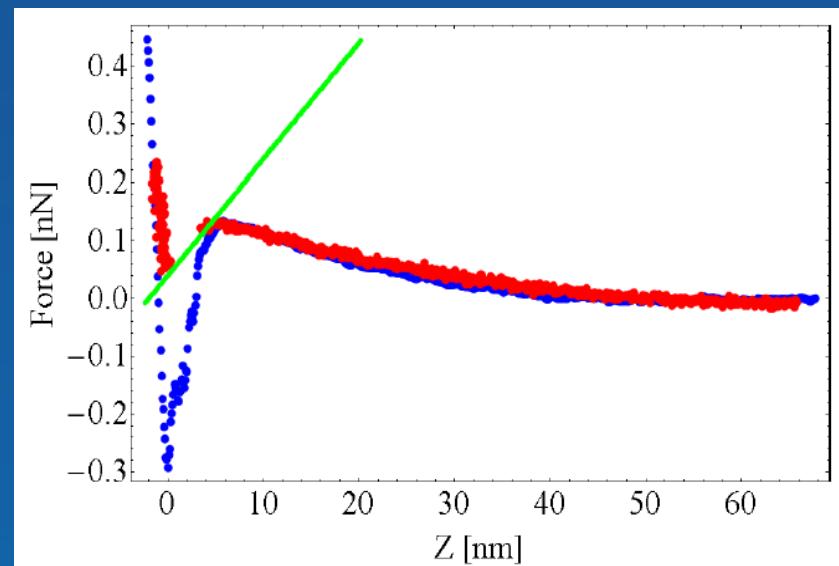
The Jump to contact

IN AIR



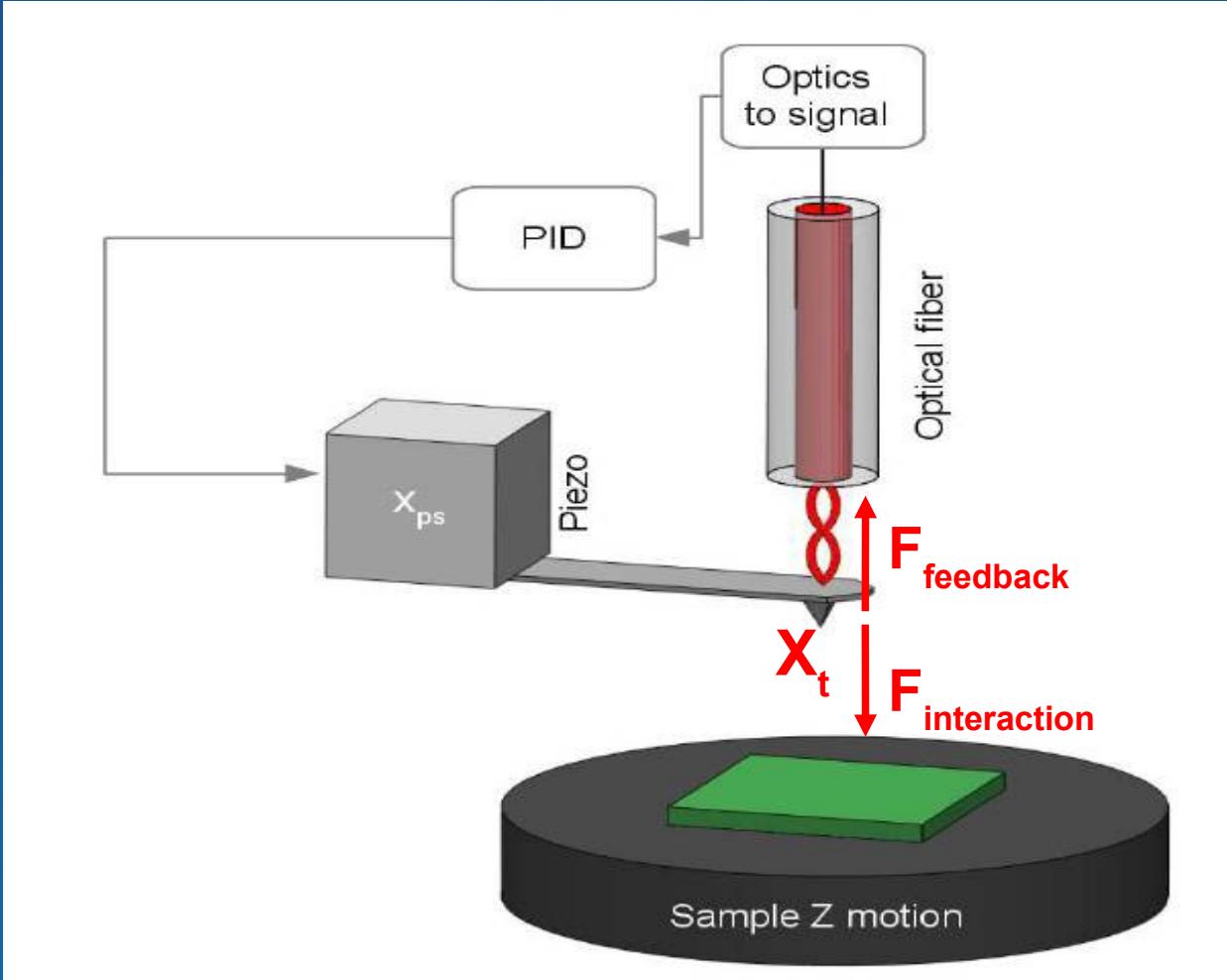
Force between a silicon probe and hydrophilic silicon native oxide surface in air

IN LIQUID



Force between a silicon nitride probe and mica in deionized water

SETUP



THE IDEA



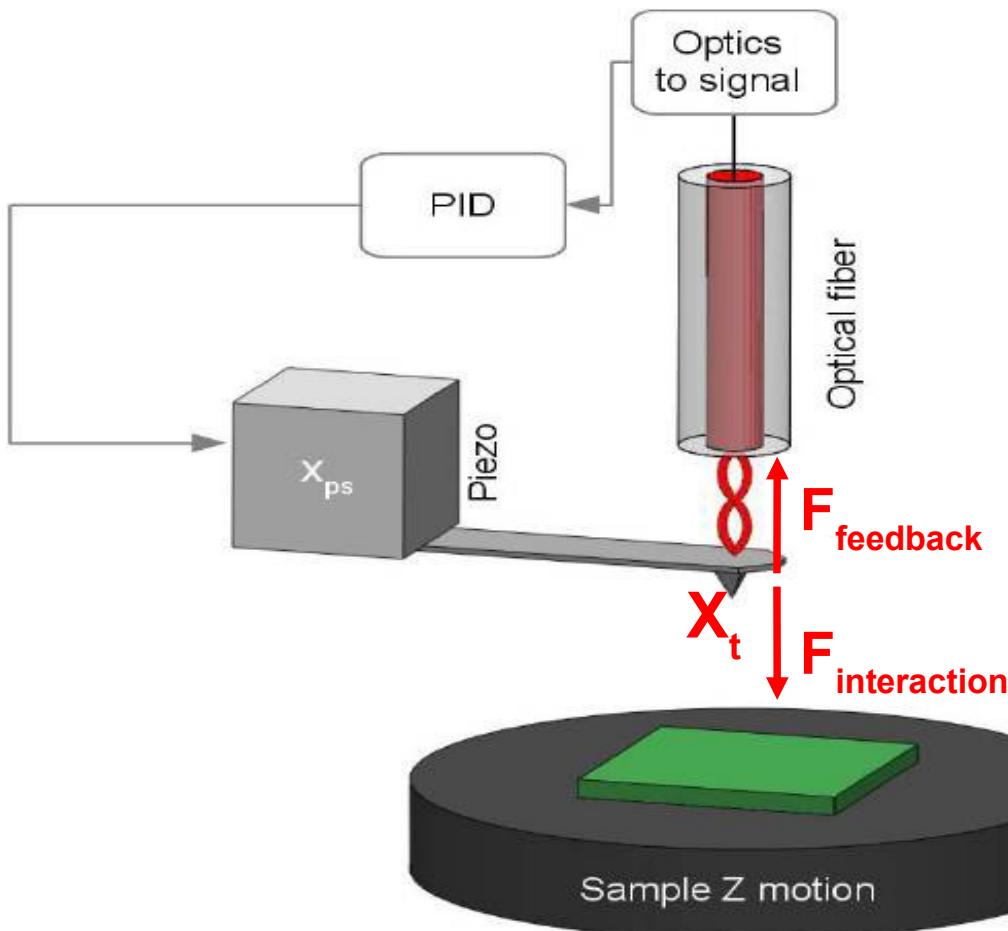
$$\sum_i \vec{F}_{i/\text{tip}} = \vec{0}$$

Sum of the force acting on the tip equal to zero

$$F_{\text{feedback}} = F_{\text{interaction}}$$

Position of the tip fixed in space

SETUP



Where

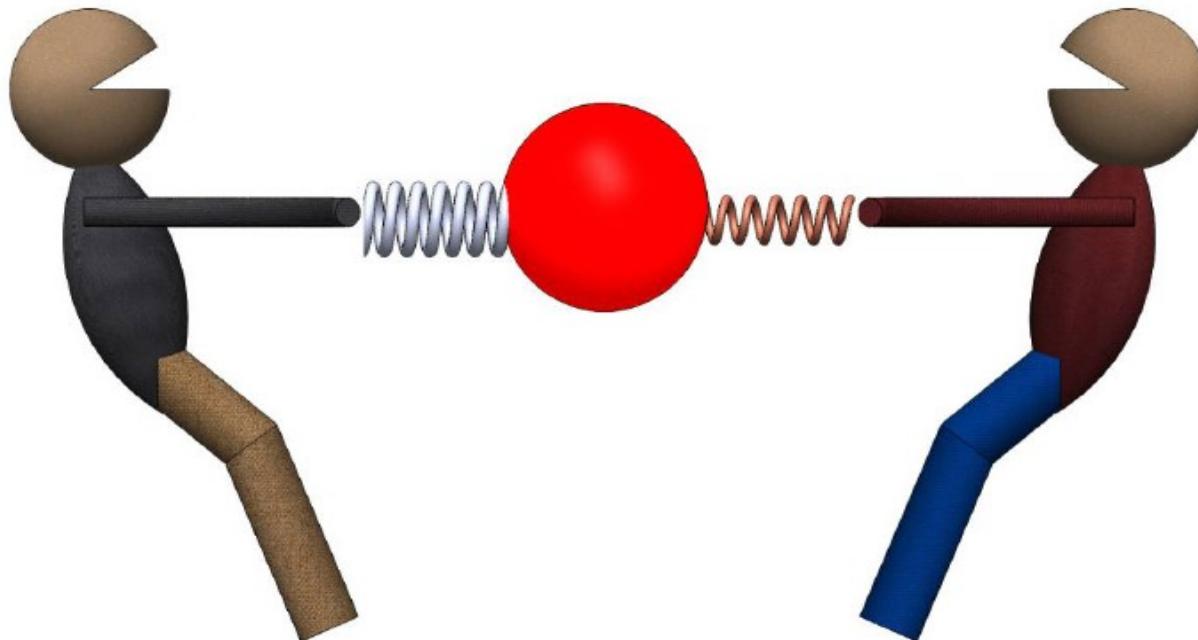
$$F_{\text{feedback}} = F_{\text{interaction}}$$

X_t is kept constant by a feedback loop

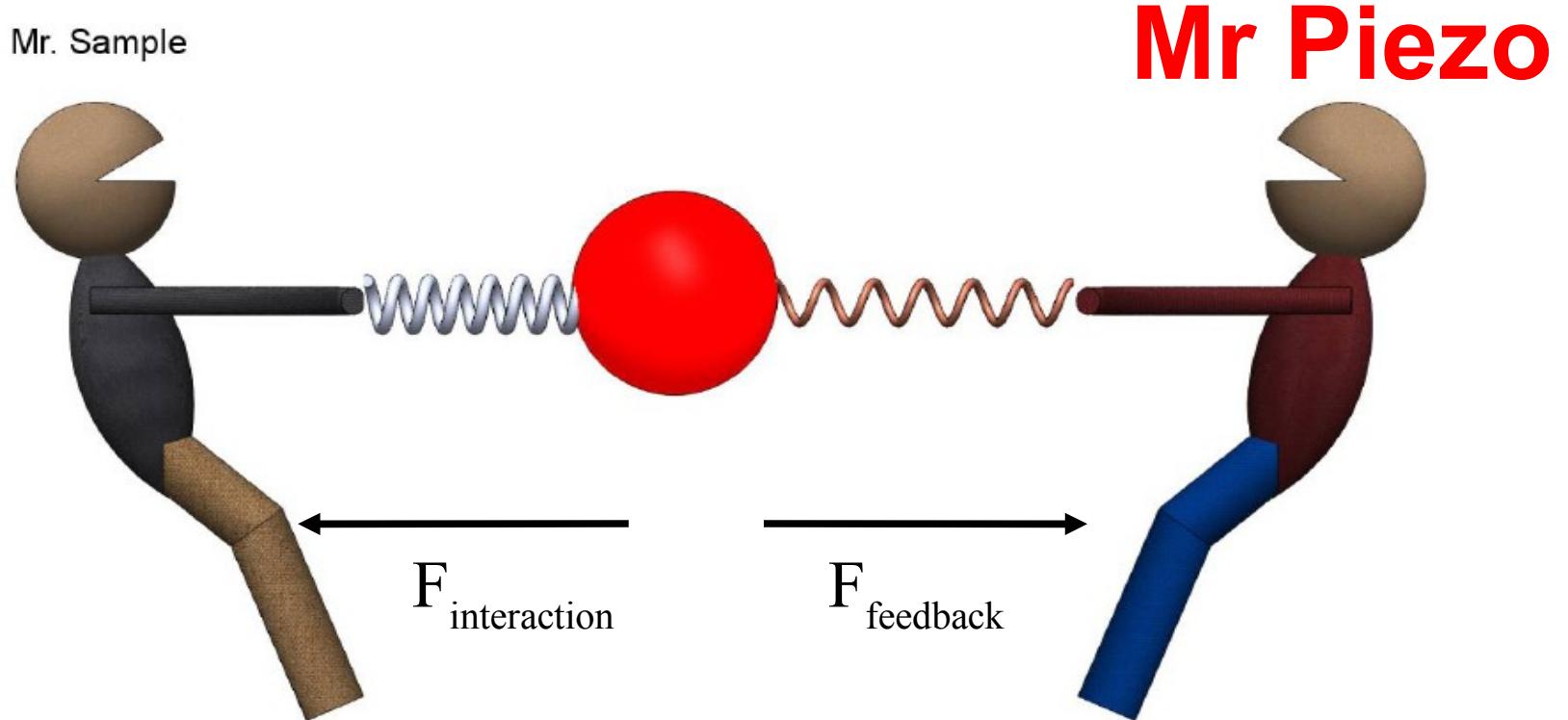
SETUP

Mr. Sample

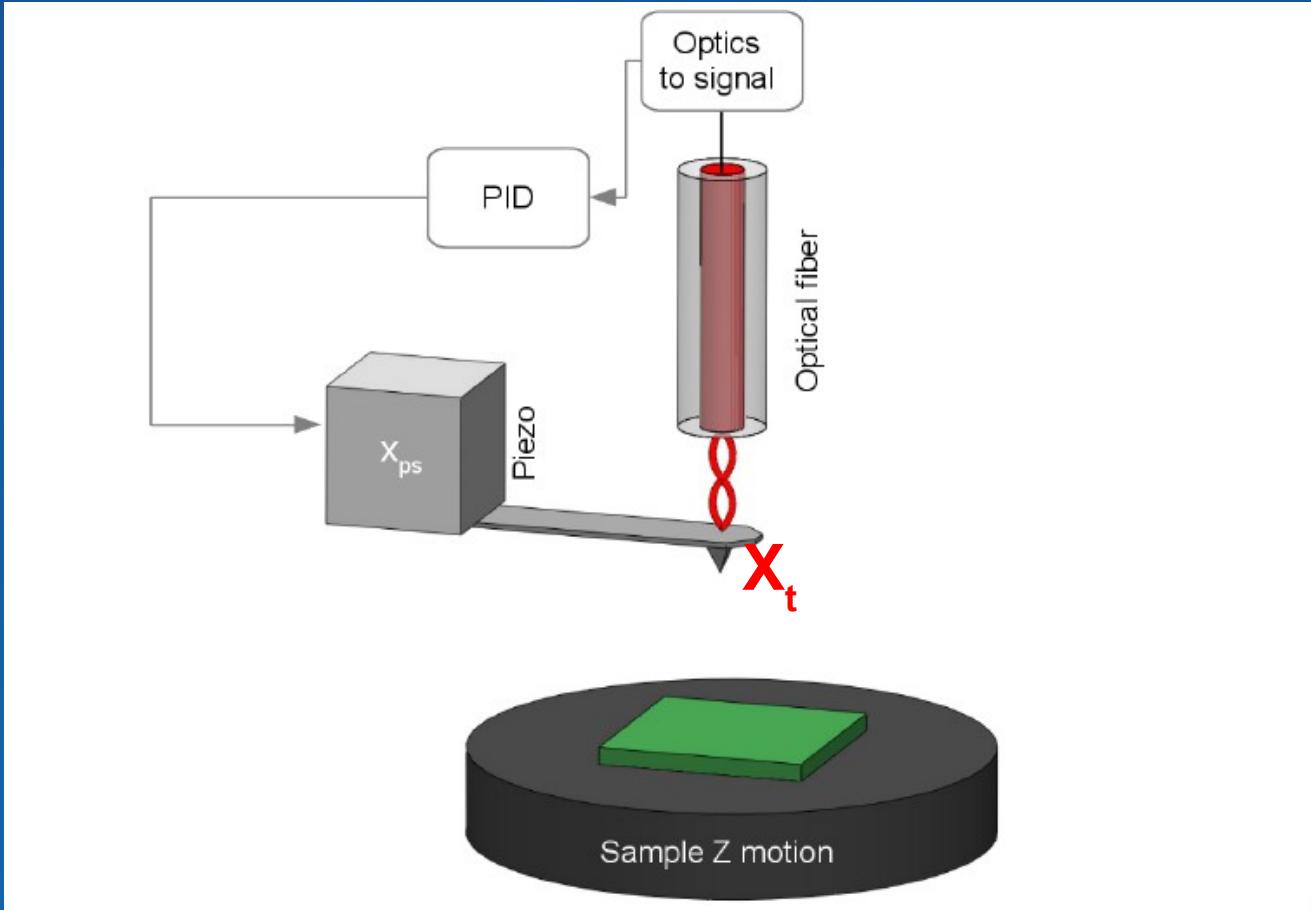
Mr Piezo



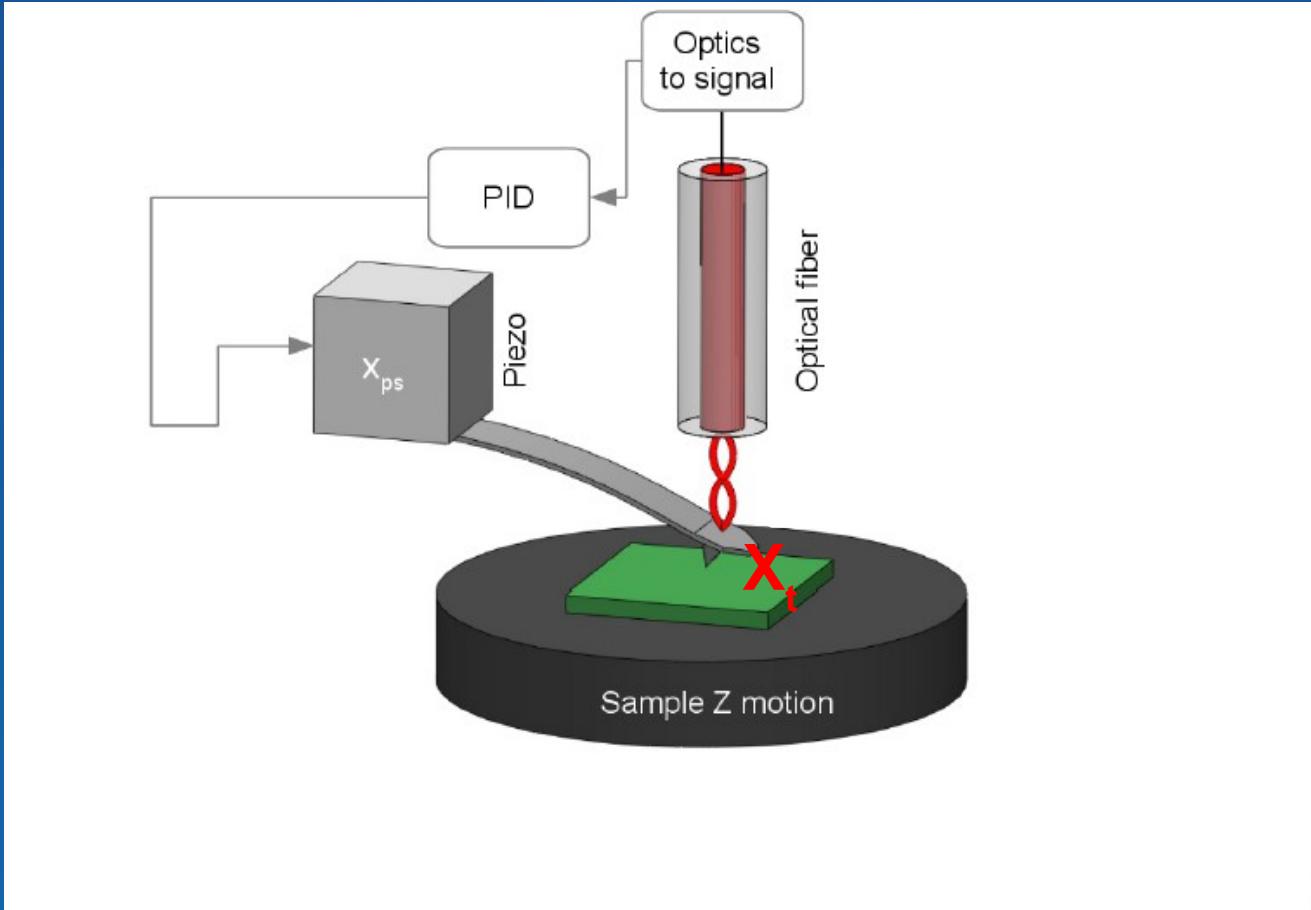
SETUP



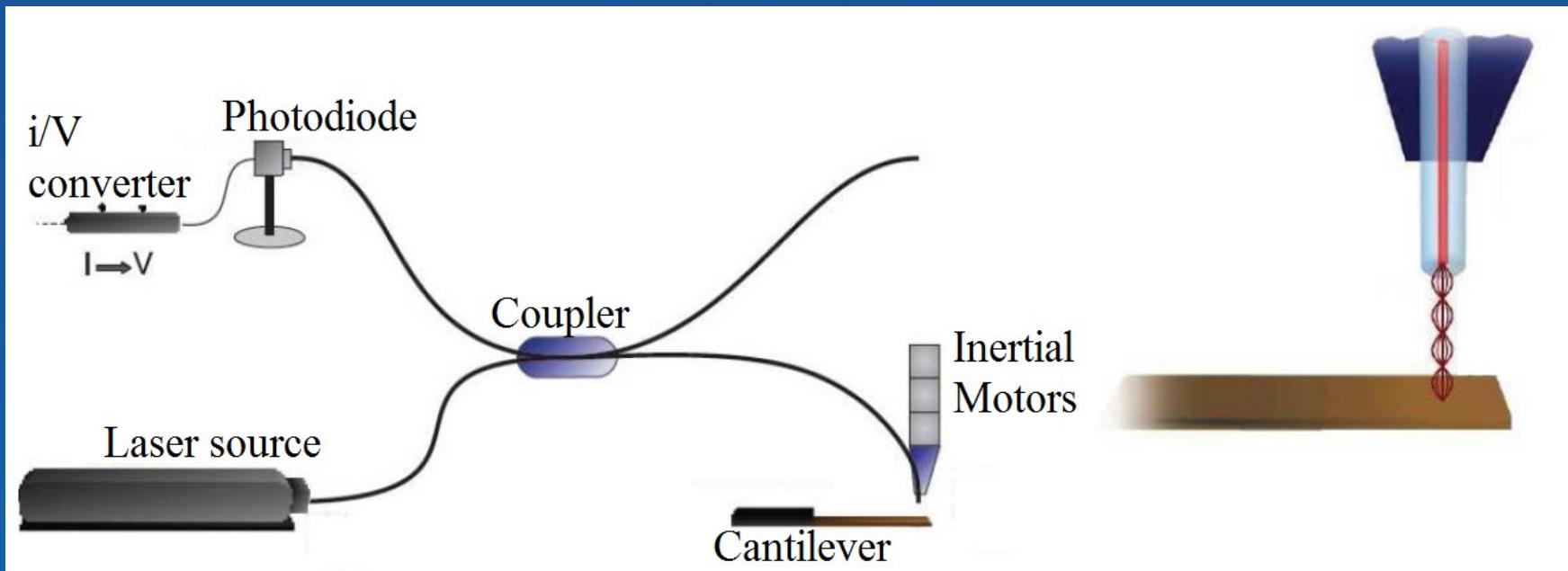
SETUP



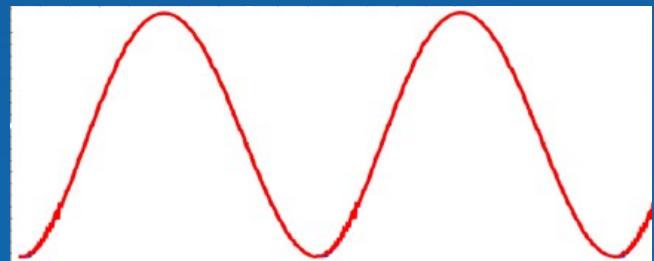
SETUP



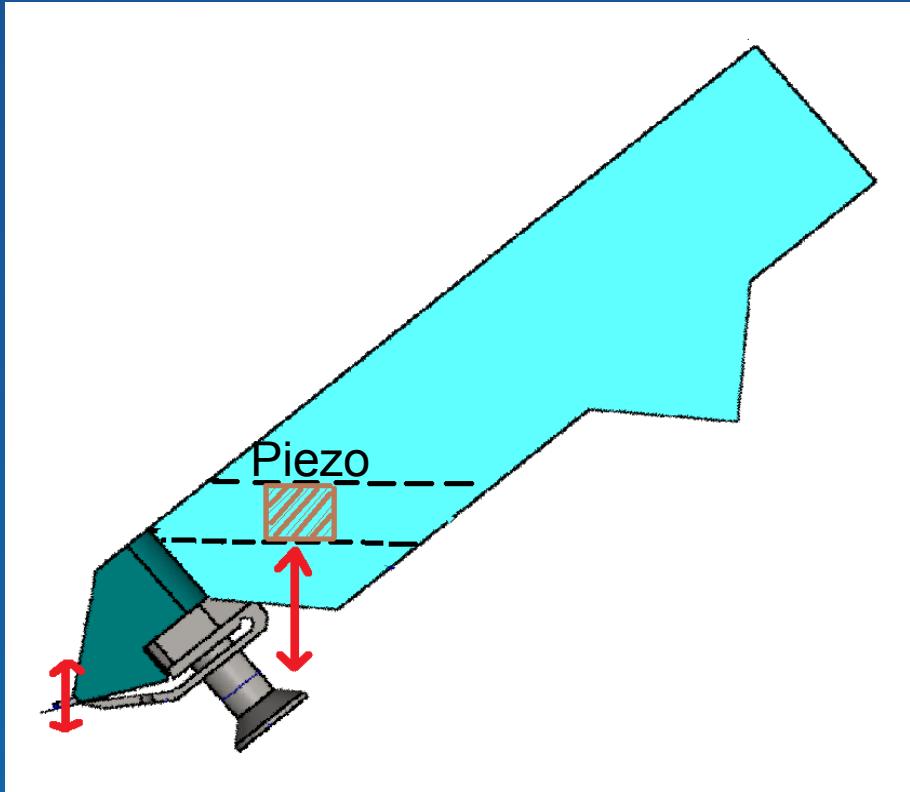
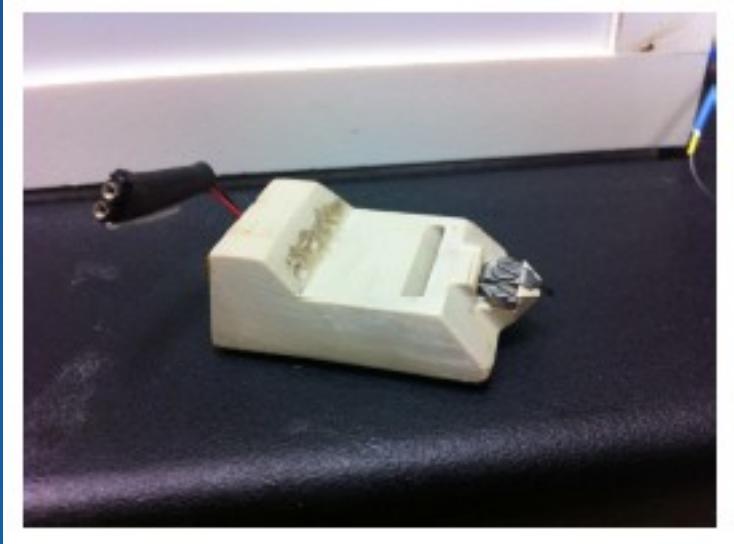
Fabry-Perot Interferometer



$$I(d) = I_0 + \Delta I_0 \sin \left(\frac{4\pi}{\lambda} d + \phi \right)$$

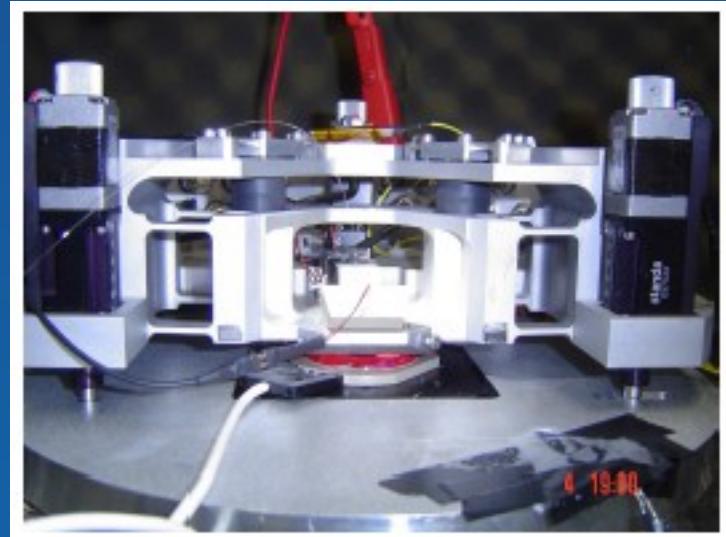
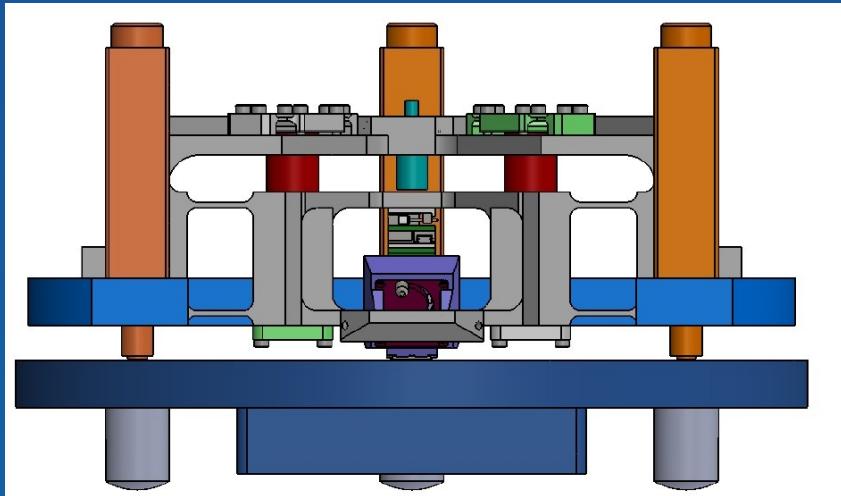


Cantilever holder



Cantilever base displacement $\approx 5 \text{ nm/V}$ applied

MICROSCOPE



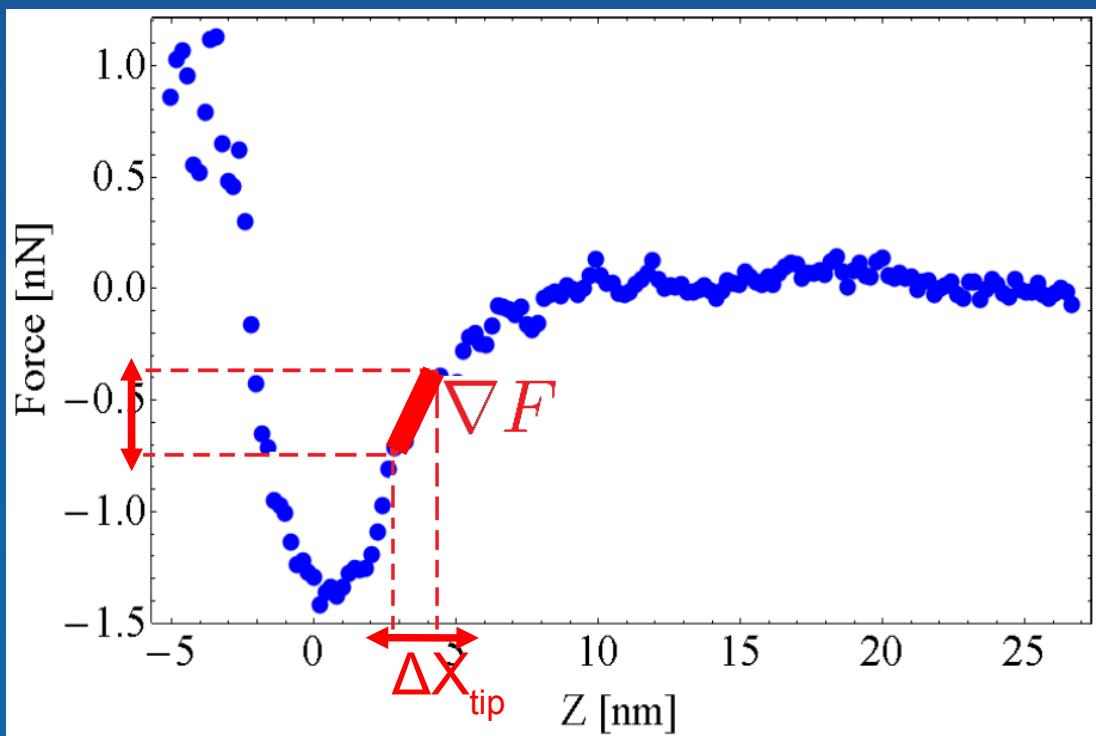
Michal Hrouzek PhD Thesis, 2004-2007

Mario S. Rodrigues Post-doc 2010-2011

DYNAMIC FFM

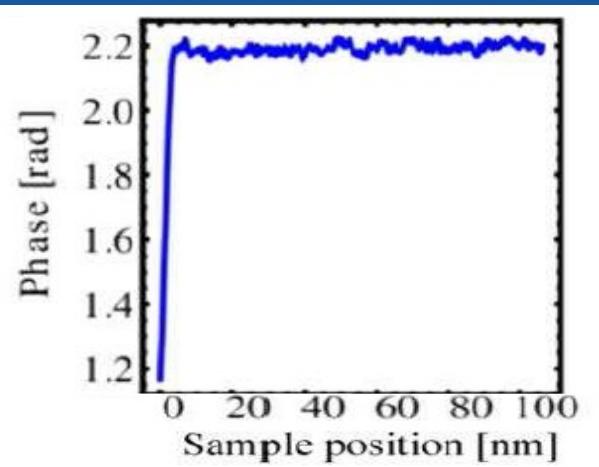
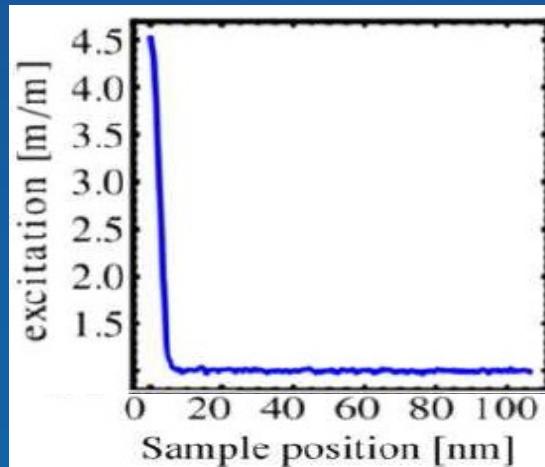
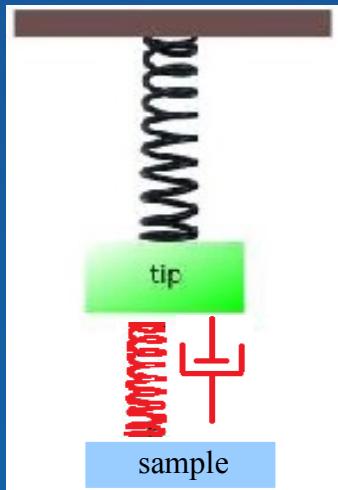
Tip oscillation

$$X_{\text{tip}}(t) = \bar{X}_{\text{tip}} + \Delta X_{\text{tip}} \cos(\omega t)$$



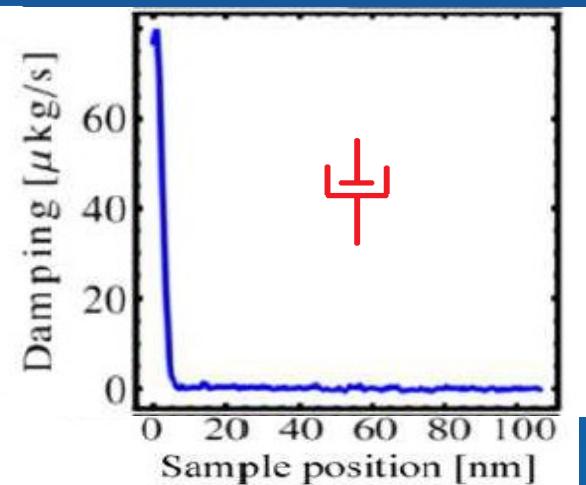
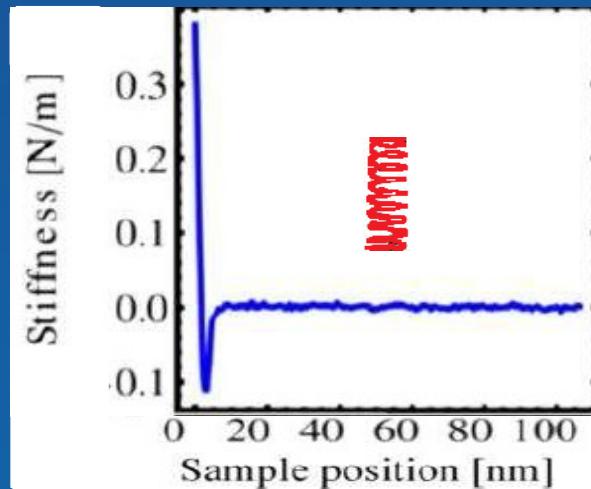
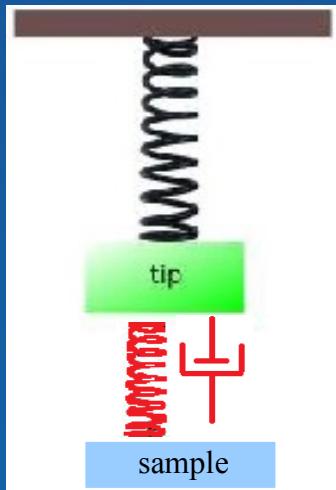
DYNAMIC FFM

RAW DATA



RAW DATA →  ?

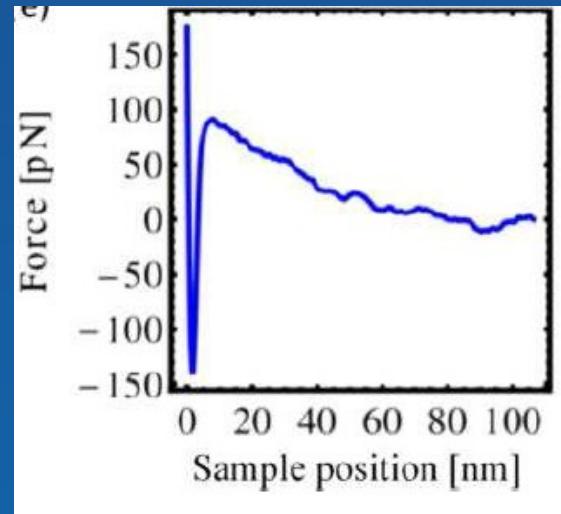
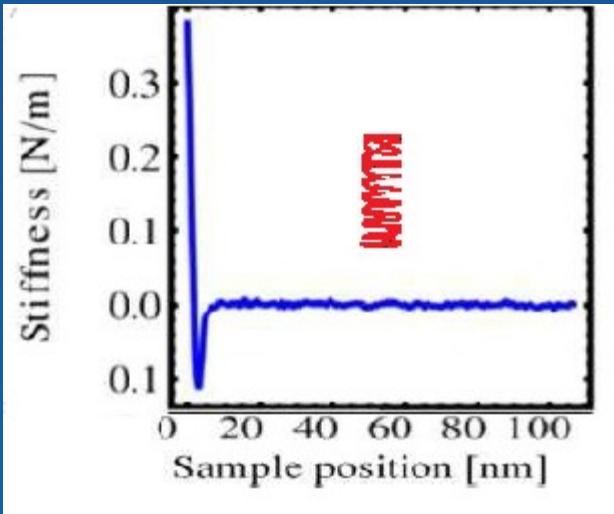
Force gradient & Dissipation



Force

$$\nabla F$$

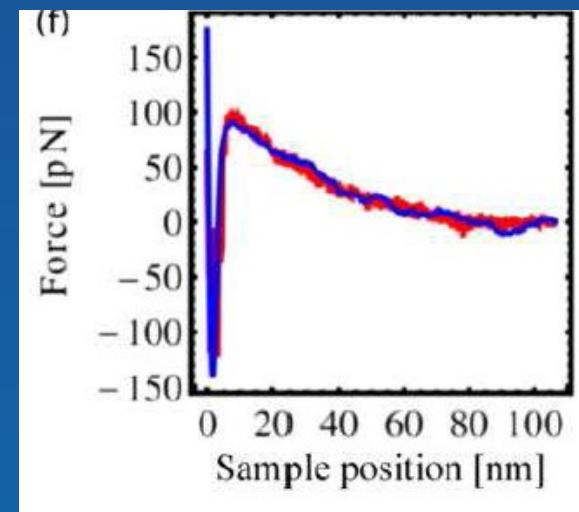
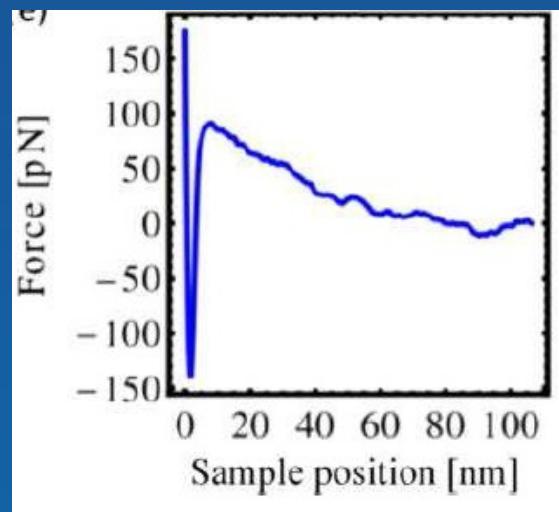
$$F_{static} = \int \nabla F dz$$



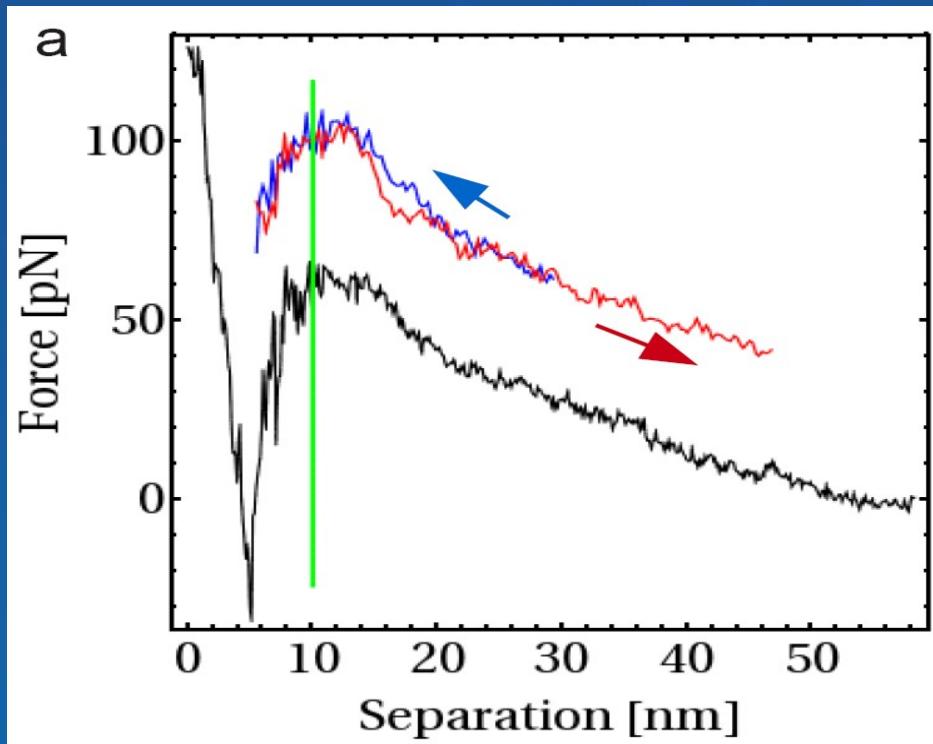
Force

$$F_{static} = \int \nabla F dz$$

$$F_{static}$$



Solid/liquid interface

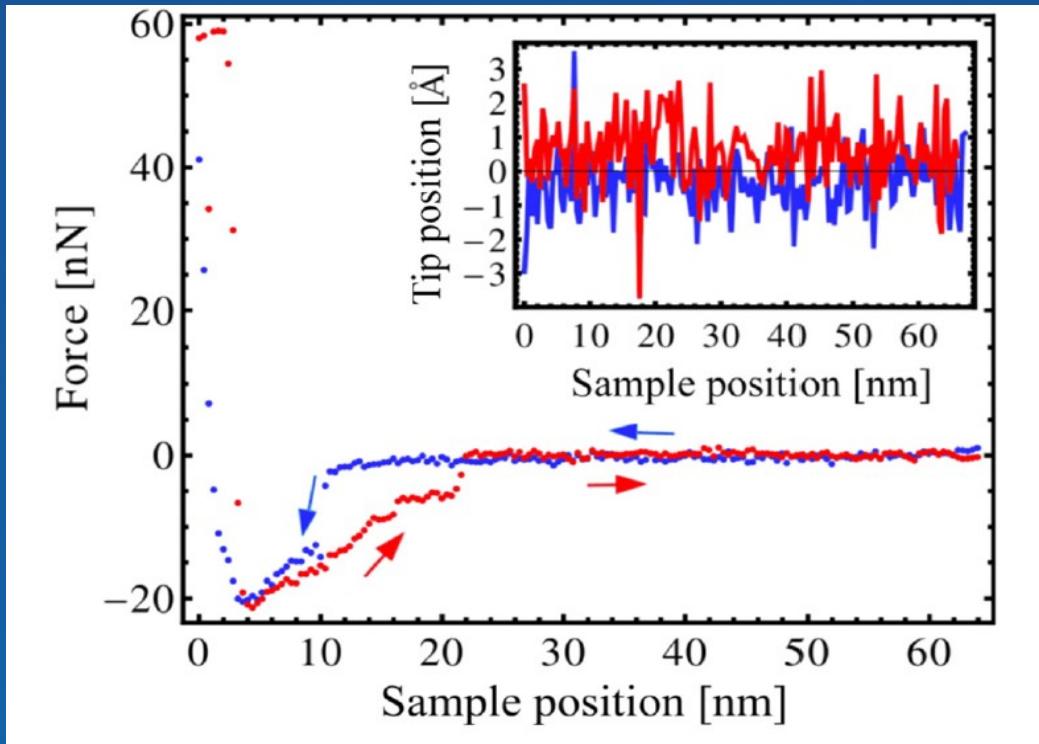


NO
HYSTERESIS

Approach – Retract force curves between a silicon nitride probe and mica in deionized water

M. S. Rodrigues, L. Costa, J. Chevrier, and F. Comin, Applied Physics Letters 101, 203105 (2012)

Solid/air interface



HYSTERESIS
DUE TO THE
SYSTEM

Approach – Retract force curves between a silicon probe and hydrophilic silicon native oxide surface in air

M. S. Rodrigues, L. Costa, J. Chevrier, and F. Comin, Applied Physics Letters 101, 203105 (2012)

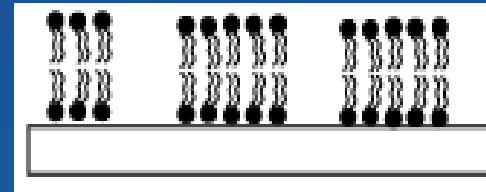
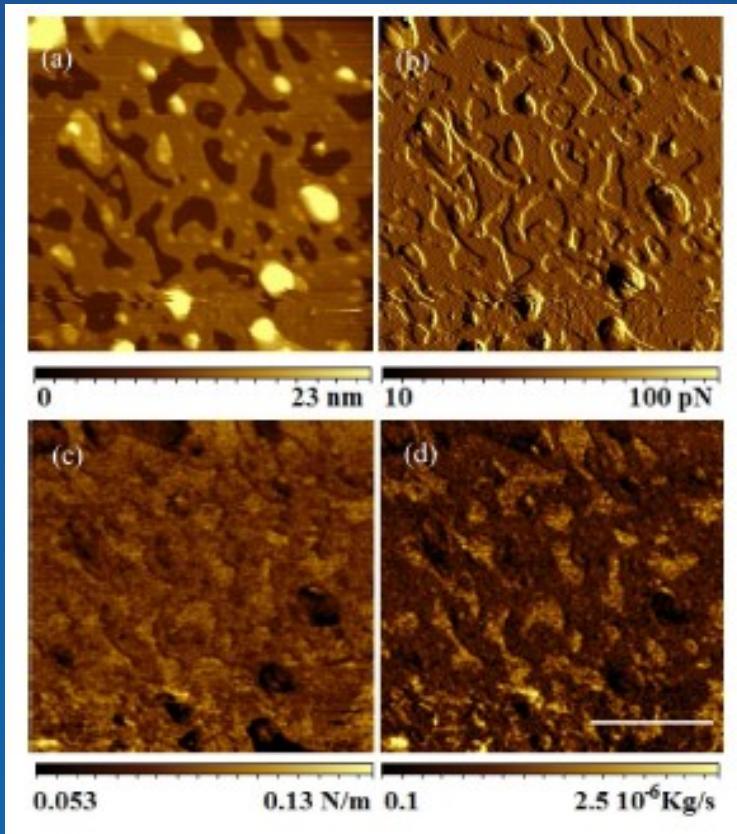
Imaging modes

Mode	Tip position	Force	Force gradient	Dissipation	Interaction nature
Constant force	constant	constant	recorded	recorded	repulsive
Constant phase	constant	recorded	“partially constant”	“partially constant”	attractive or repulsive
Constant excitation	constant	recorded	“partially constant”	“partially constant”	attractive or repulsive

Imaging modes applied to the study of soft biological samples

Phospholipids DSPE

Page 73 of the manuscript



- a) Topography
- b) Force
- c) Stiffness
- d) Dissipation

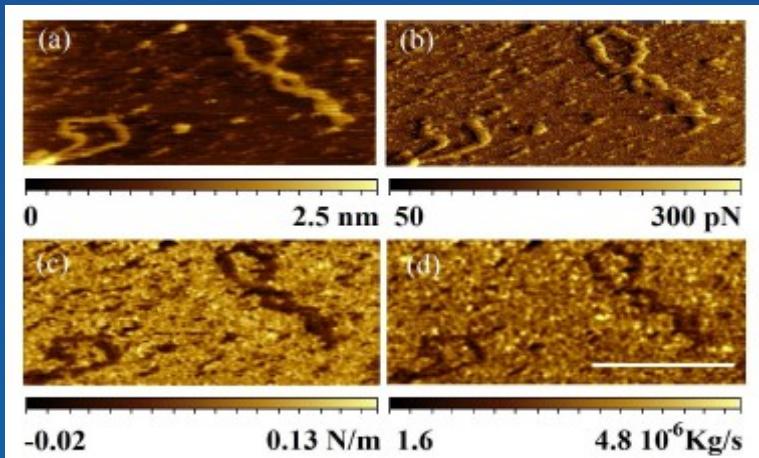
Excitation frequency of the tip
not linked to resonance

Young modulus $E \approx 7 \text{ MPa}$

DNA

Pages 76-77 of the manuscript

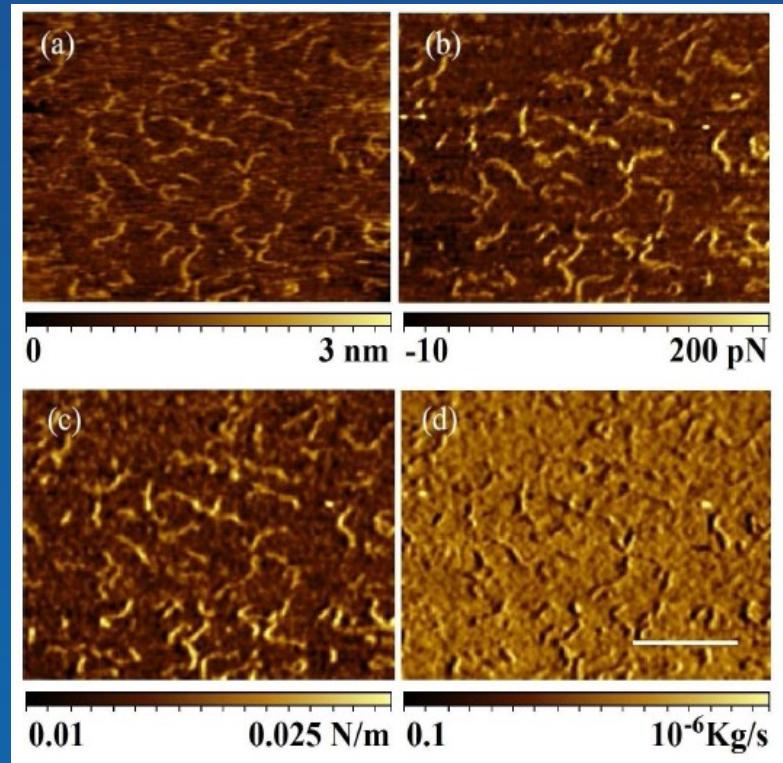
Constant Force



- a) Topography
- b) Force
- c) Stiffness
- d) Dissipation

Excitation frequency
of the tip
not linked to cantilever
resonance

Constant Dissipation



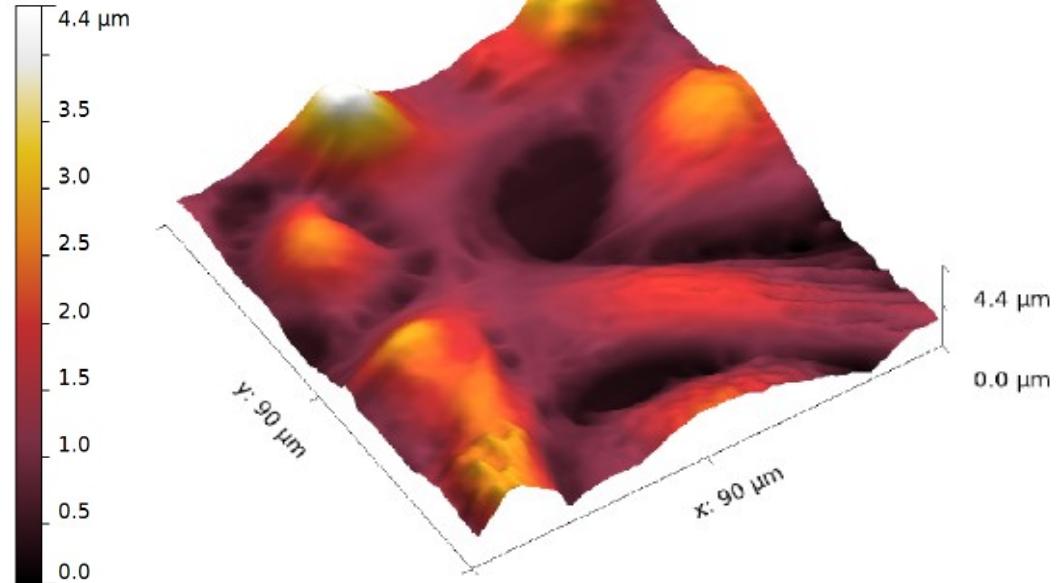
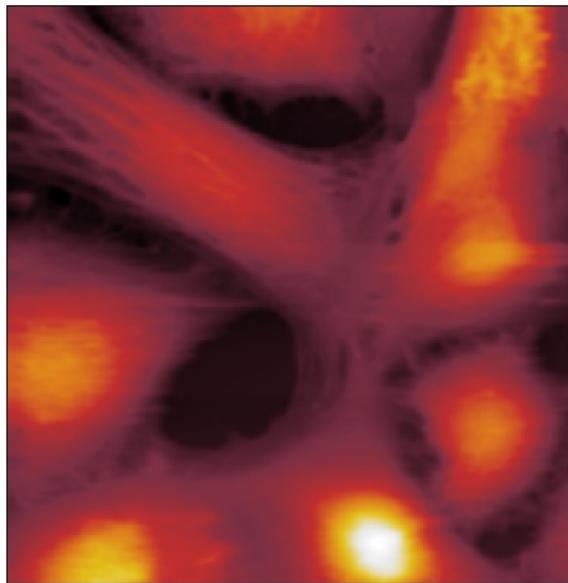
Living Cells PC12

TUNABLE EXCITATION FREQUENCY

↓

Viscoelastic spectroscopy

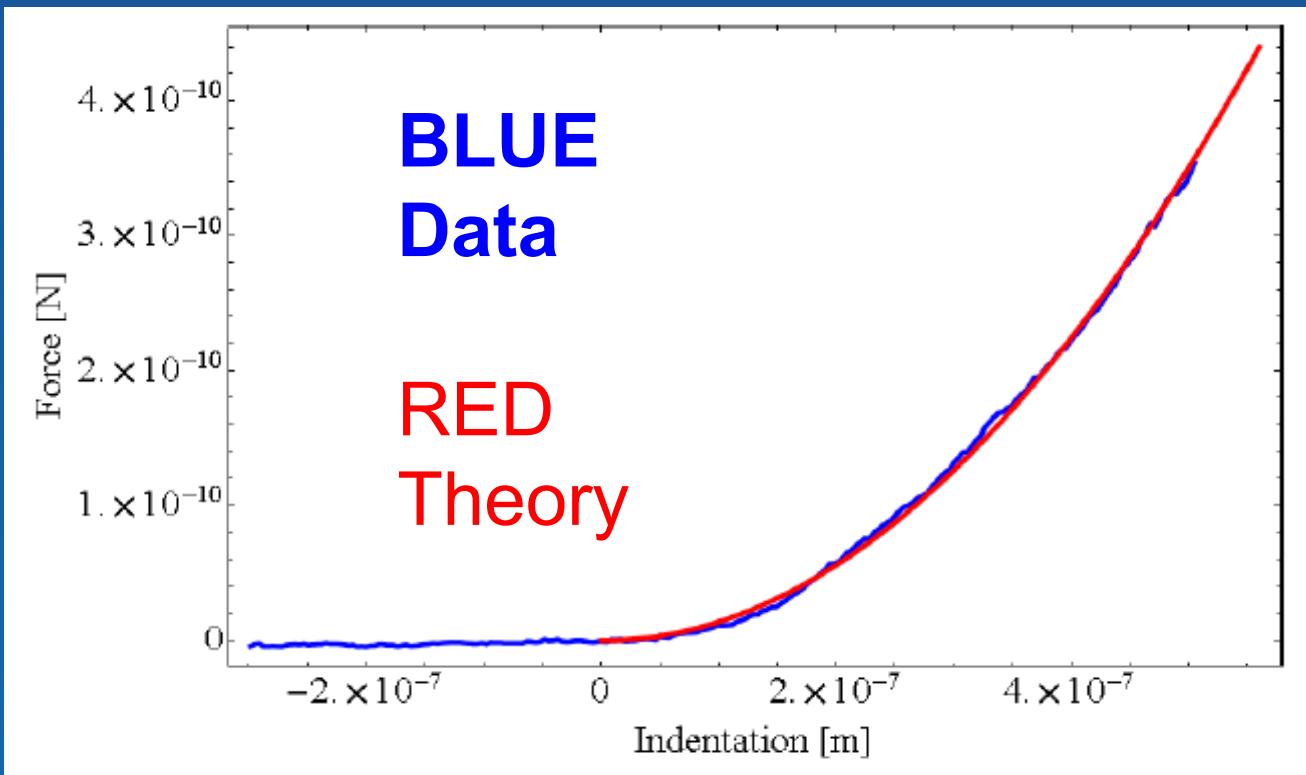
Candidate: Living cell PC12, in MEM - 1% Strepto-Penicillin



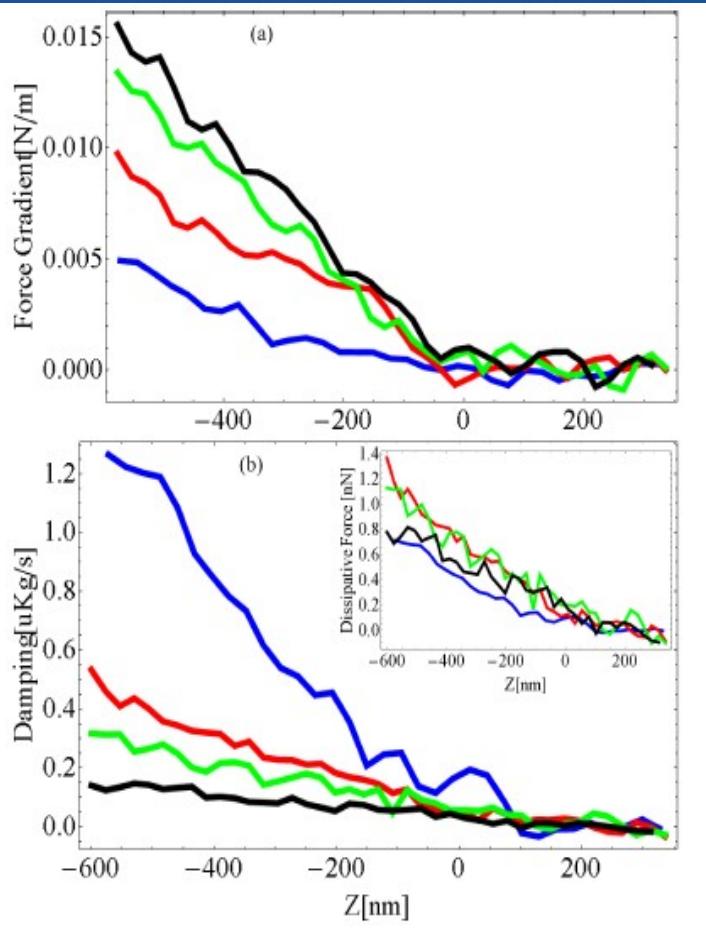
Static indentation

Quasi-static conditions: Young modulus ≈ 1 kPa

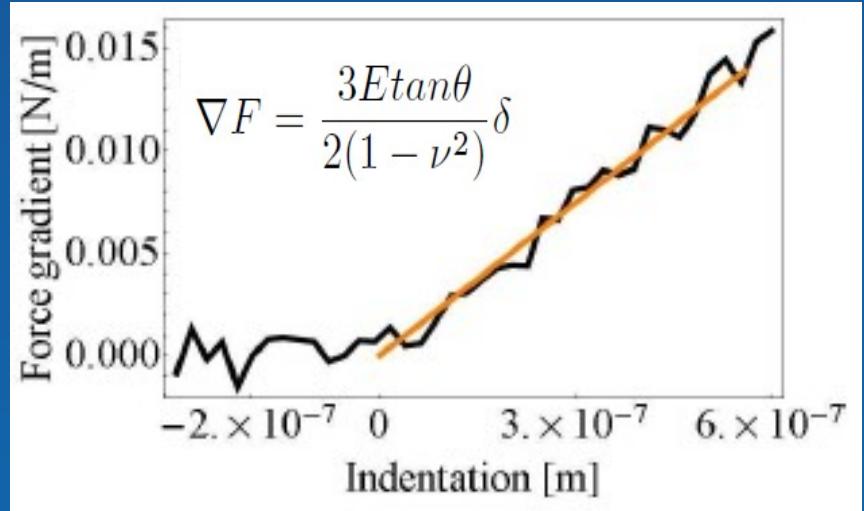
$$F = \frac{3Etan\theta}{4(1 - \nu^2)}\delta^2$$



FFM indentation



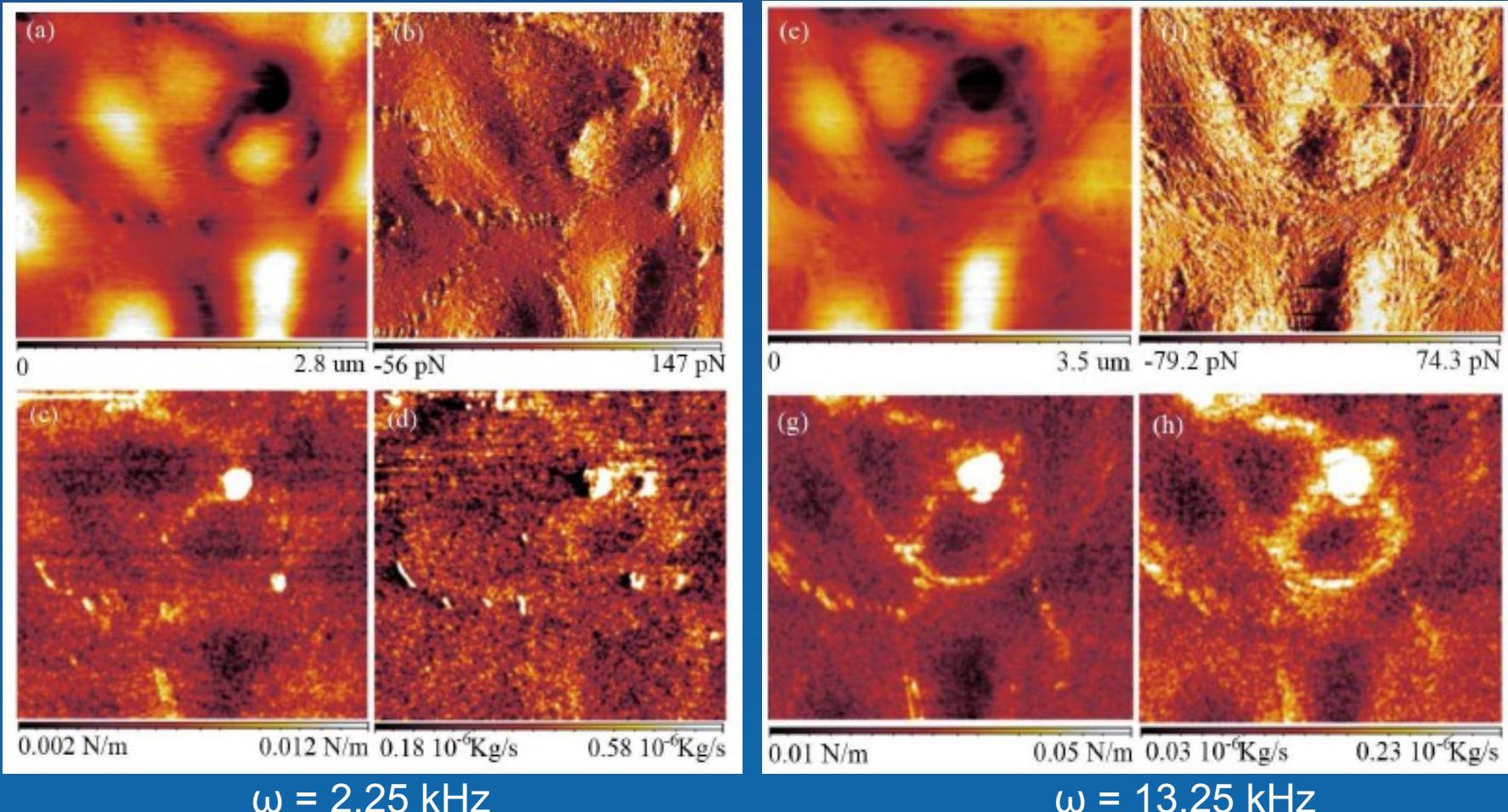
Blue = 1.13 kHz
Red = 5.13 kHz
Green = 7.13 kHz
Black = 11.13 kHz



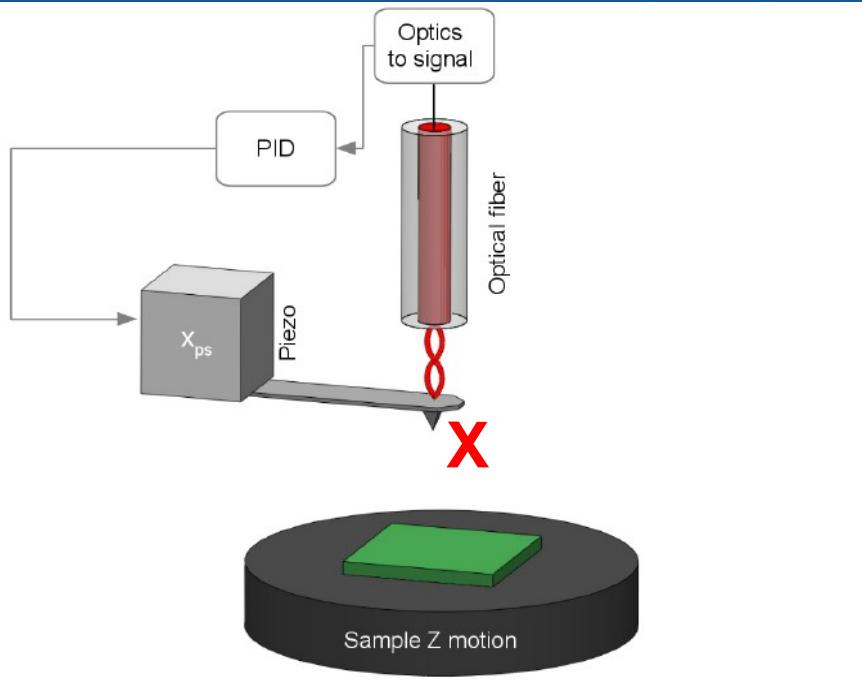
At 10 kHz, Young modulus ≈ 30 kPa

Mapping mechanical properties

Page 94 of the manuscript



Feedback loop



Motion of the tip described by

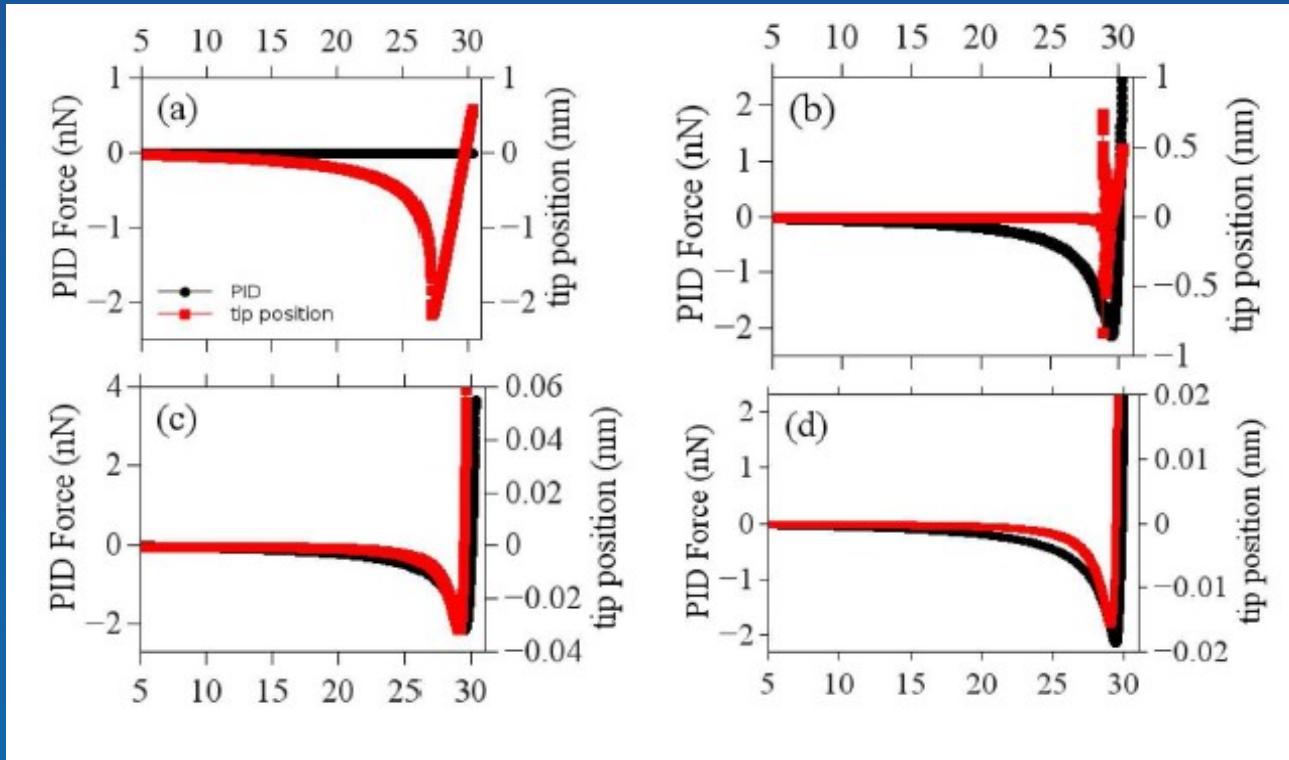
$$m\ddot{x} + \gamma\dot{x} + kx = F_{control} + F_{tip-sample}$$

$$F_{control} = -g_P x + -g_D \dot{x} - g_I \int_0^t x dt$$

Simulations

Lever stiffness = 1 N/m

attractive force gradient = -1 N/m



- a) no gains
- b) just Integral gain
- c) Proportional gain equal to lever stiffness (fast approach) + Integral gain
- d) Proportional gain equal to lever stiffness (slow approach) + Integral gain

Stability conditions

$$F_{ts} = F_{ts,0} - k_{ts}x - \gamma_{ts}\dot{x}$$

$$k_t = k + k_{ts}$$

$$\omega_0^2 = \frac{k}{m} \quad Q = \frac{\omega_0}{\Delta\omega}$$

Stability conditions

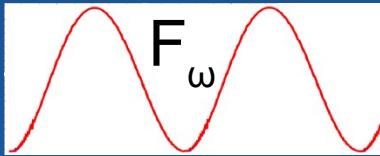
$g_P > -k_t$ Mechanical stability of the tip

$$g_I < \frac{\omega_0}{3Q}(k_t + g_P) \quad \text{under-damped}$$

$$g_I < Q\omega_0 \frac{(k_t + g_P)^2}{k} \quad \text{over-damped}$$

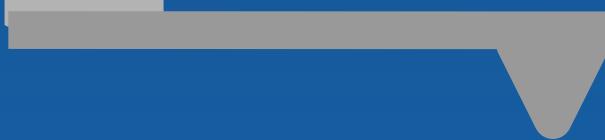
Speed

Dynamic FFM

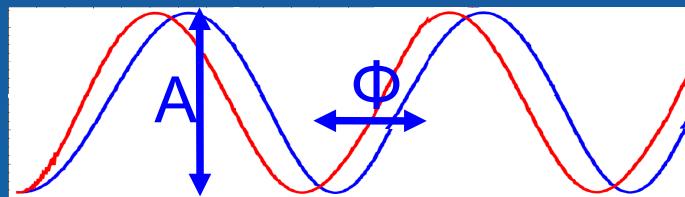


$$A = \frac{F_\omega}{\sqrt{[(k_t + g_P) - m\omega^2]^2 + [(\gamma_t + g_D)\omega - \frac{g_I}{\omega}]^2}}$$

Piezo



$$\phi = \arctan \left[\frac{(\gamma_t + g_D)\omega - \frac{g_I}{\omega}}{(k_t + g_P) - m\omega^2} \right]$$



Cantilever Transfer Function depends on PID gains
 F_ω is the harmonic excitation

M. S. Rodrigues, L. Costa, J. Chevrier, and F. Comin, submitted to Journal of applied Physics (2013)

Master equations

Force gradient

$$k_{ts} = F_{\omega\infty} [n \cos(\phi) - \cos(\phi_\infty)]$$

Dissipation

$$\gamma_{ts} = \frac{F_{\omega\infty}}{\omega} [n \sin(\phi) - \sin(\phi_\infty)]$$

$$F_{ts} = F_{ts,0} - k_{ts}x - \gamma_{ts}\dot{x}$$

$$n = F_\omega / F_{\omega\infty}$$

$$F_{\omega\infty} \cos(\phi_\infty) = k - m\omega^2$$

$$F_{\omega\infty} \sin(\phi_\infty) = \gamma\omega$$

Limits

Speed: defined by the maximum integral gain employed

$$g_I = \frac{\omega_0}{3Q}(k_t + g_P) \quad \text{under-damped}$$
$$g_I = Q\omega_0 \frac{(k_t + g_P)^2}{k} \quad \text{over-damped}$$

Force sensitivity: given by the lever stiffness. No difference between AFM and FFM
The FFM simply let you measure attractive forces where AFM cannot.

Force gradient sensitivity: given by the effective lever stiffness.
No difference between AFM and FFM.

Jump to contact: avoided for force gradient 5 times stiffer than the cantilever

Perspectives (1)

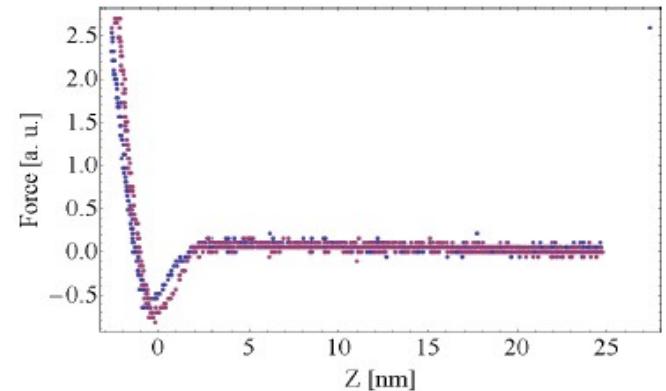
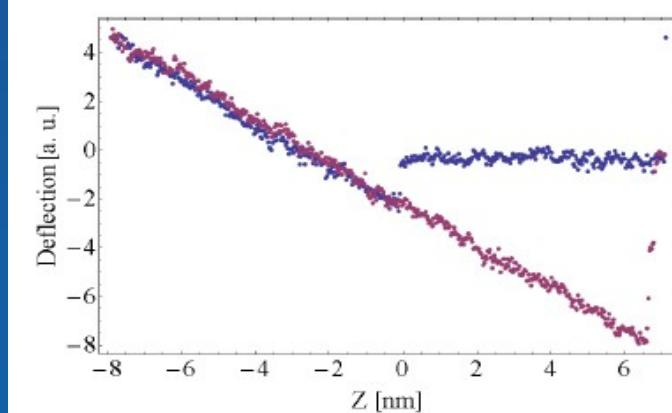
Time – dependent interaction forces

$$F_{static} \neq \int \nabla F(\omega = \omega_R) dz$$

- Viscoelastic materials
- Capillary condensates
- Ligand-Receptor binding

Perspectives (2)

FFM with optical beam deflection systems



Measure the lever angle → counteract on the cantilever base angle

Surface Science Lab. Team (past & present)



ESRF:
Chloe Zubieta
Sriarsha Puranik
Veronique Mayeaux
Harald Muller
Irina Snigireva
Nuria Benseny-Cases
Lin Zhang
Pascal Dideron
Pascal Bernard
SCM group

EMBL:
Emily Newman
Aurelian Dordor

External help:
P.E. Mihliet
Neil Thomson
Jean-Luc Pellequer

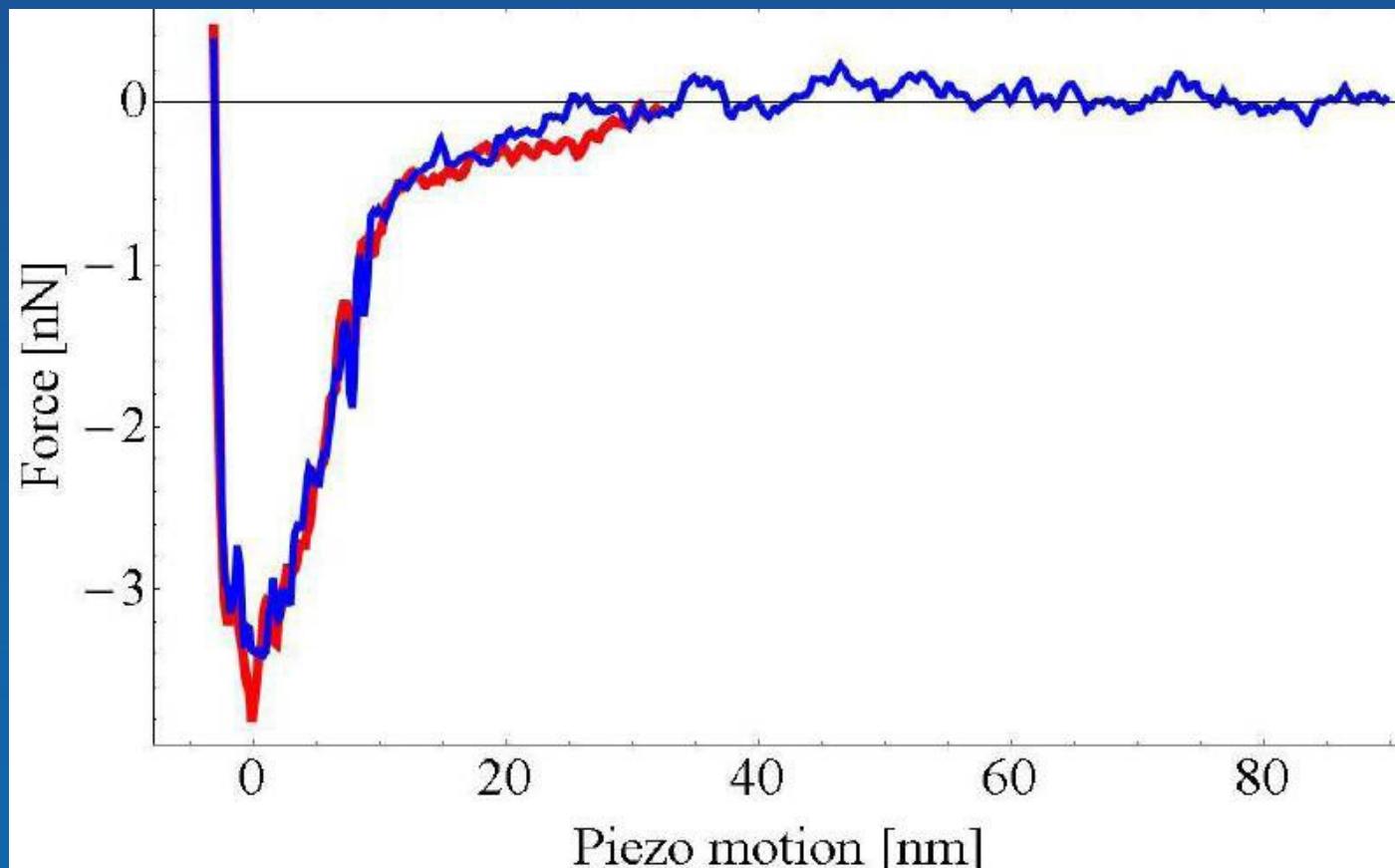
ILL:
Giovanna Fragneto
Jess Webster

My EUROPEAN COLLEAGUES
My FRENCH FRIENDS

..... and you for your kind attention

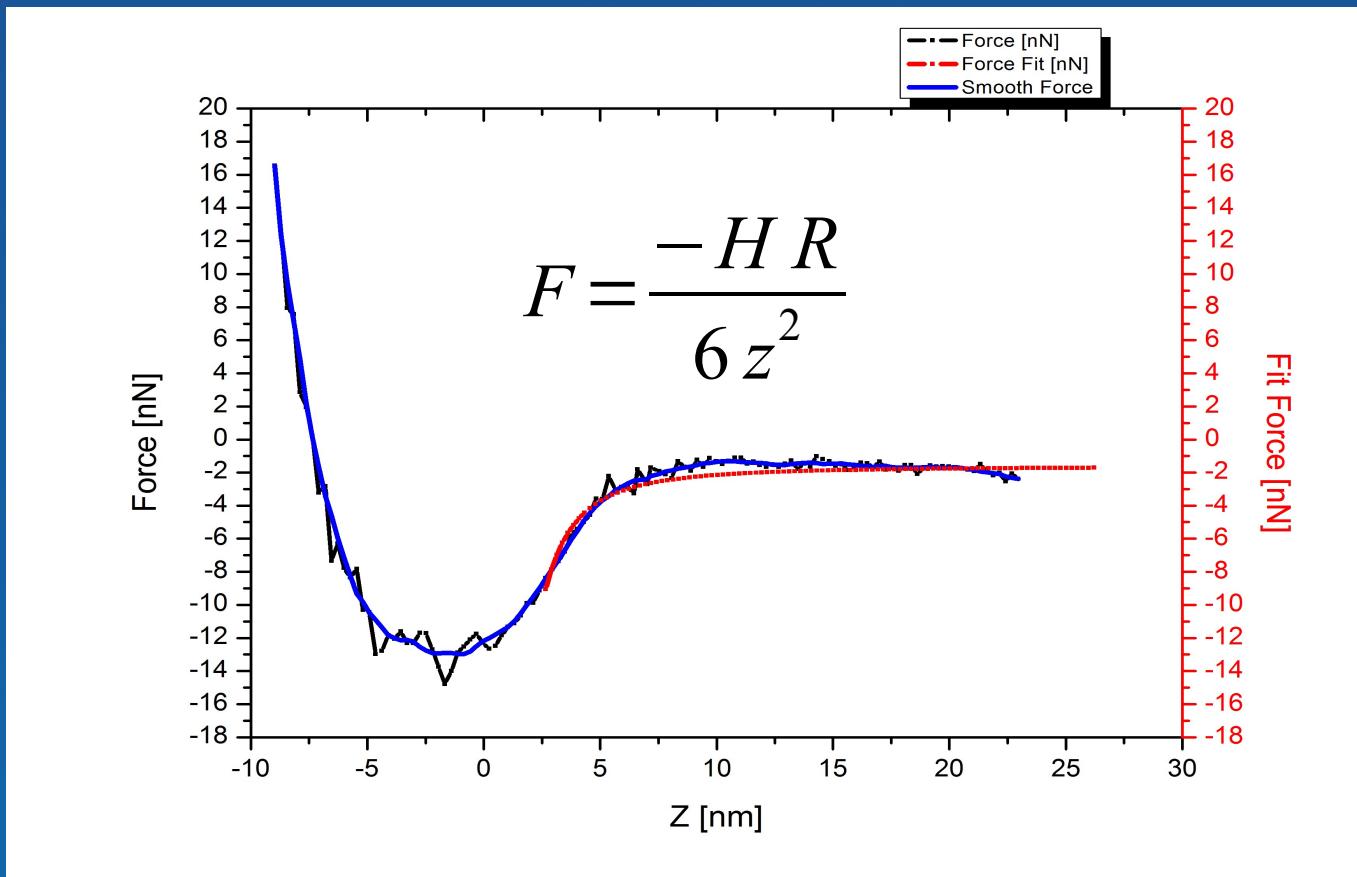
Additional Slides

Approach-Retракt on HOPG



Additional Slides

Fit for Van der Waals

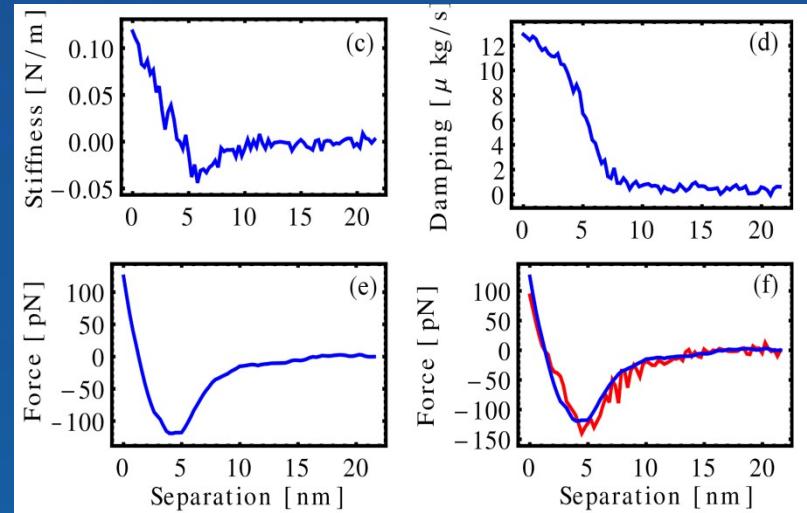
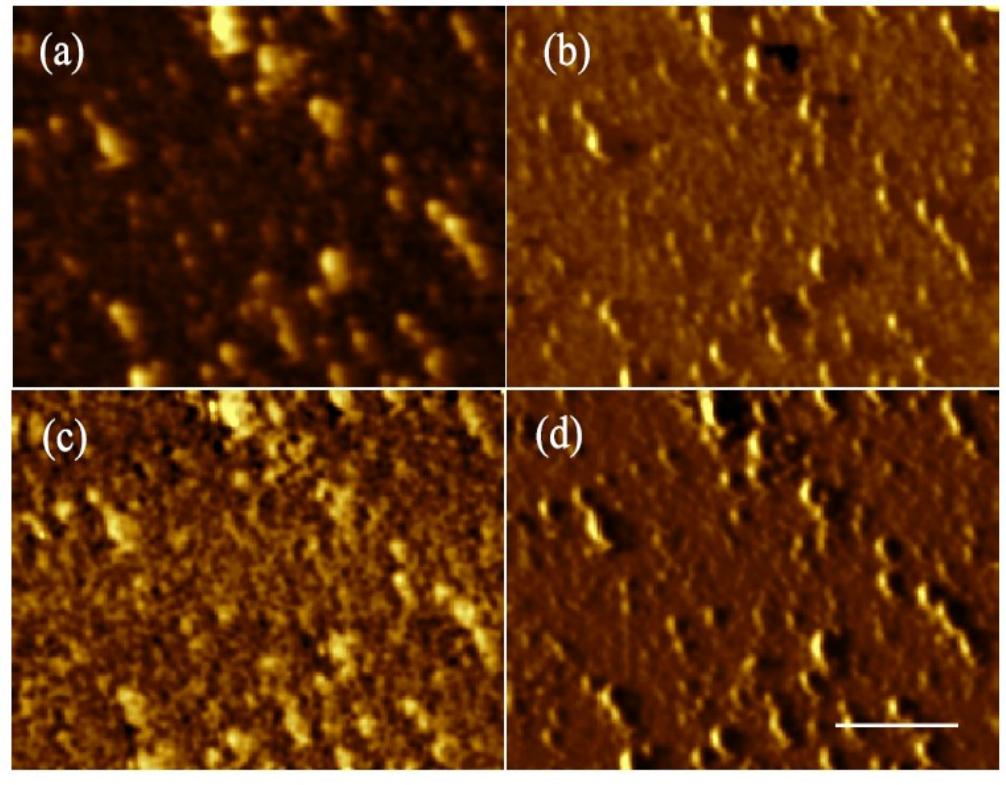


Additional Slides

Rupture cell membrane



Additional Slides



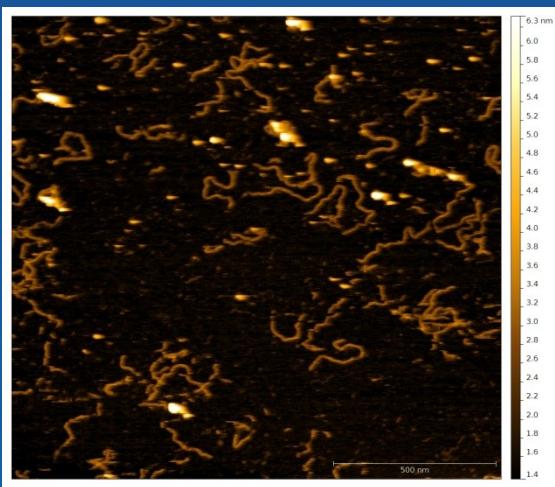
Tank Binding Kinase (TBK1) and Optineurin (OPTN) protein complexes on mica in 20 mM HEPES and 5 mM MgCl₂

(a) topography, (b) force, (c) stiffness, (d) damping

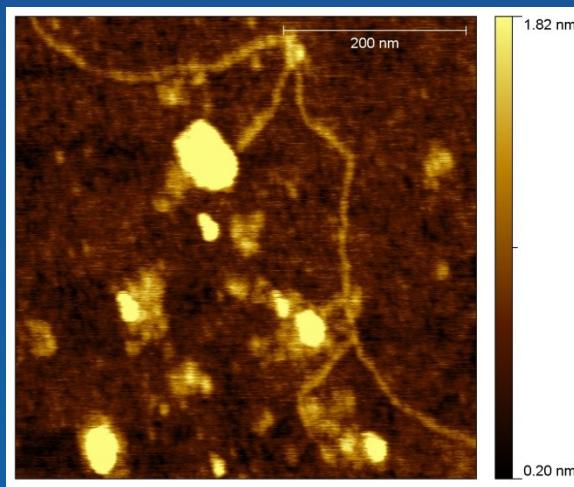
The full color scale is a) 24nm, b) -300pN, c) -0.04 N/m, d) 5 $\mu\text{kg/s}$

Additional Slides

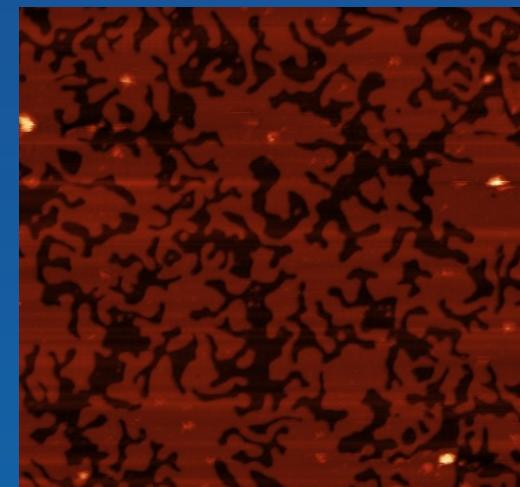
Biomolecules images with a commercial AFM (Asylum MFP3D)



DNA



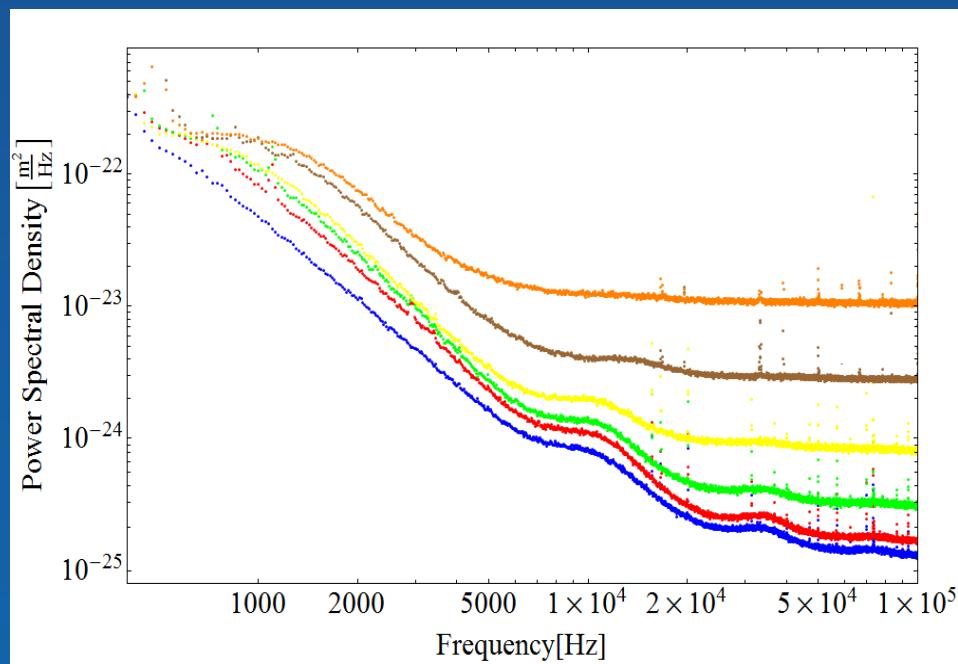
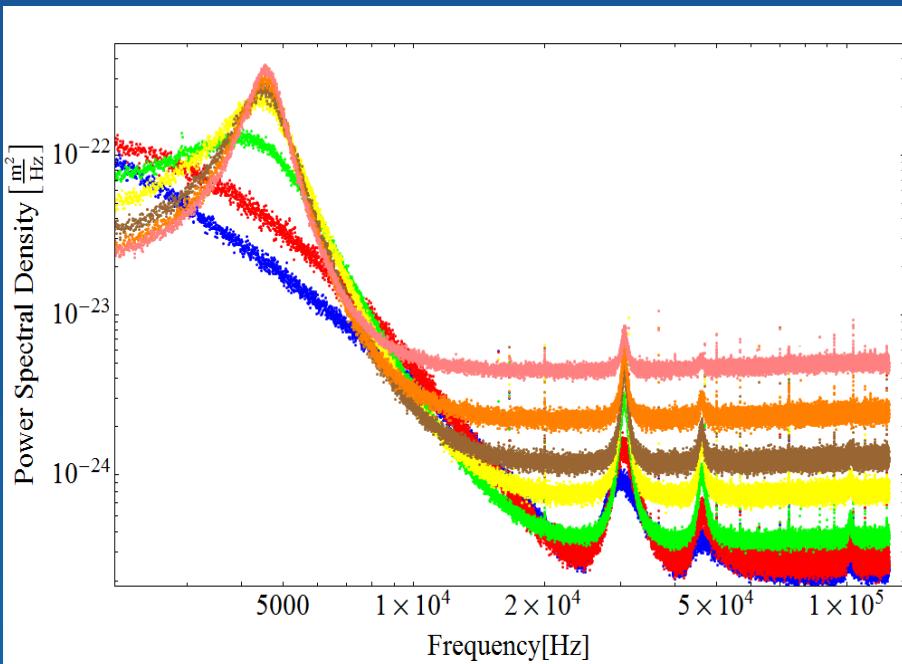
Proteins
TBK1 OPTN



LIPIDS

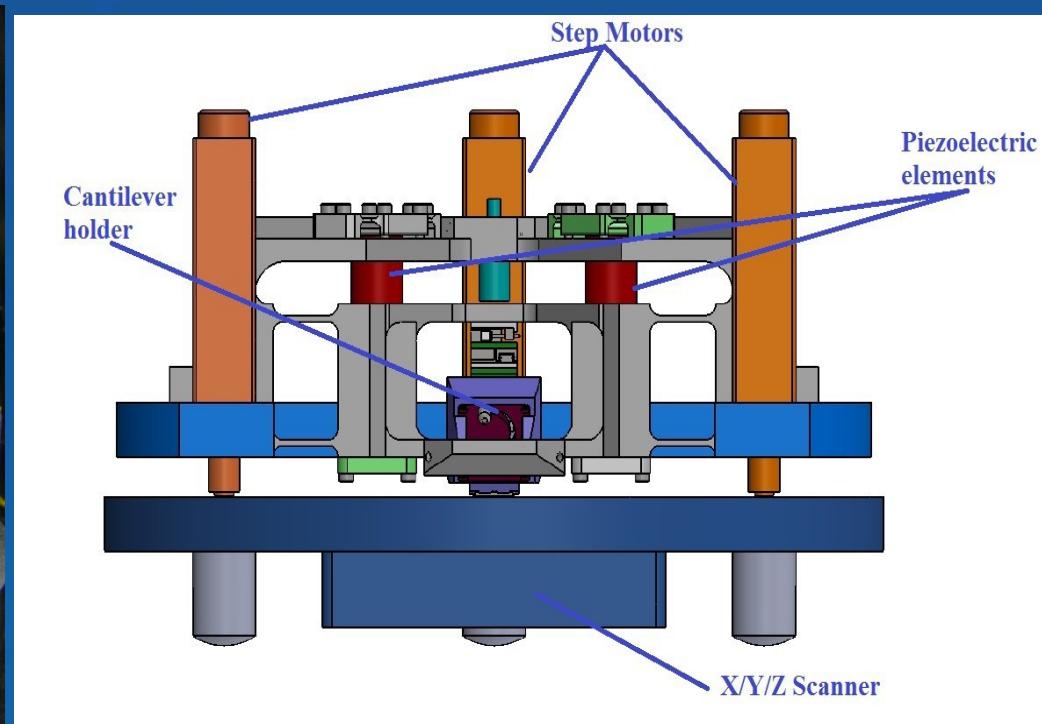
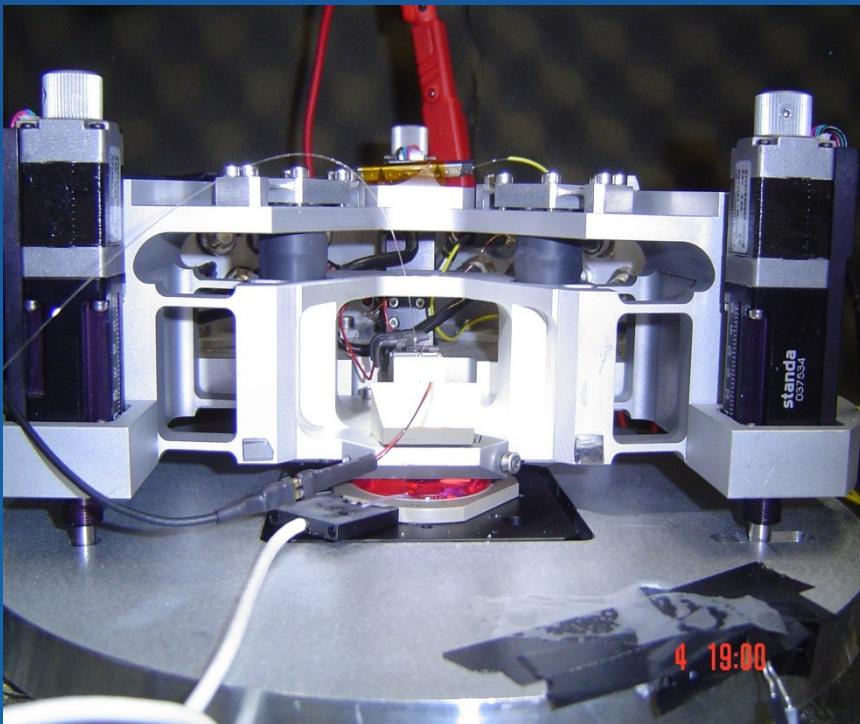
Additional Slides

Tip power spectral density in air and liquid as a function of the tip-fiber distance



Additional Slides

The Force Feedback Microscope



Additional Slides

Another FFM image on PC12 living cells

