Introduction SUSY solutions Twist and GCG De Sitter String theory flux vacua on twisted tori and Generalized Complex Geometry



PhD defence, in presence of

Iosif BENA, Michela PETRINI, Henning SAMTLEBEN, Dimitrios TSIMPIS, Daniel WALDRAM, Jean-Bernard ZUBER

arXiv:0804.1769 by D. A.

arXiv:0903.0633 by D. A., R. Minasian, M. Petrini arXiv:1003.3774 by D. A., E. Goi, R. Minasian, M. Petrini

01/07/2010, LPTHE, UPMC Univ Paris 6, France

SUSY solutions Twist and GCC

De Sitter

Conclusion

Introduction

• String theory considers extended objects: strings, of typical length l_s .

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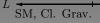
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• LHC \approx giant microscope



Zoom on particles we know, and even tinier things.

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Zoom on particles we know, and even tinier things. But quantum gravity effects are still at smaller length.

By "zooming-out" from string theory, can we recover particle physics, or predict things to be discovered at the LHC?

• Problem

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• Problem : superstring theory has several characteristic features not observed



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 - Dimensions of space-time: 1+9



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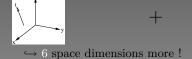
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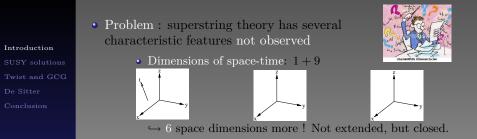
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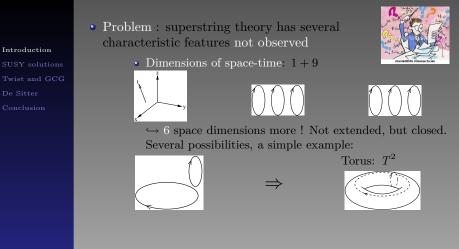


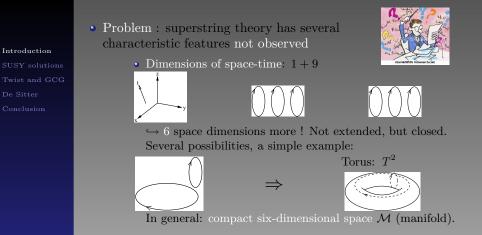


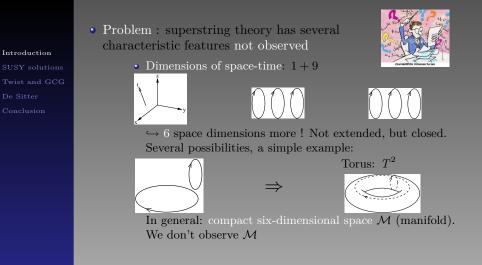


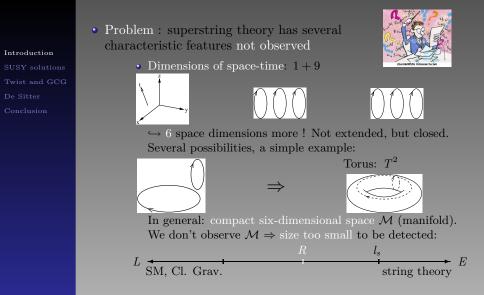
 \hookrightarrow 6 space dimensions more ! Not extended, but closed. Several possibilities, a simple example:

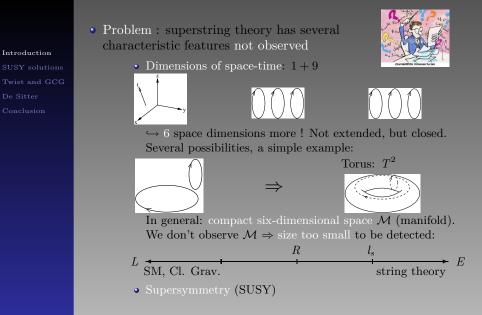


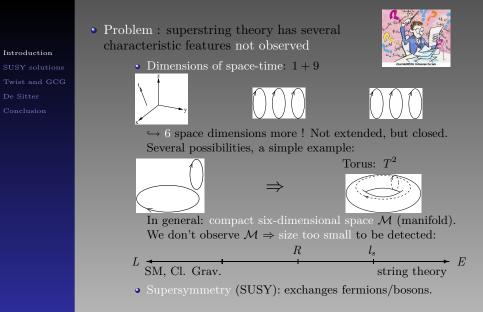


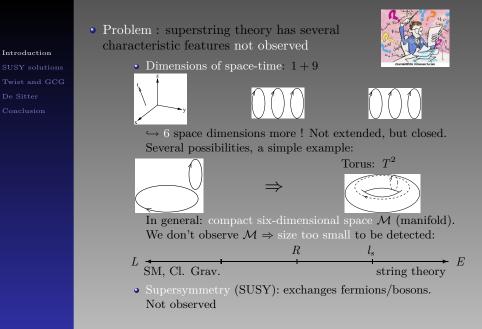


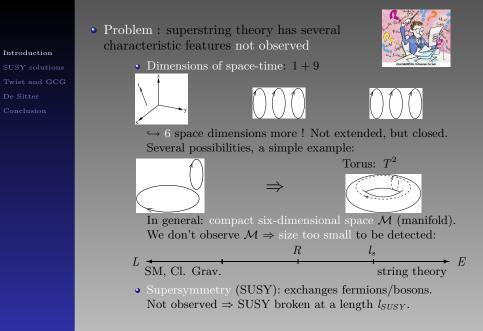


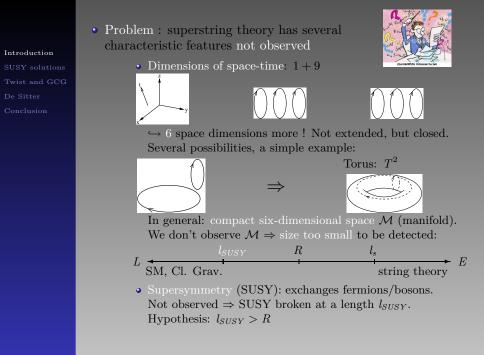


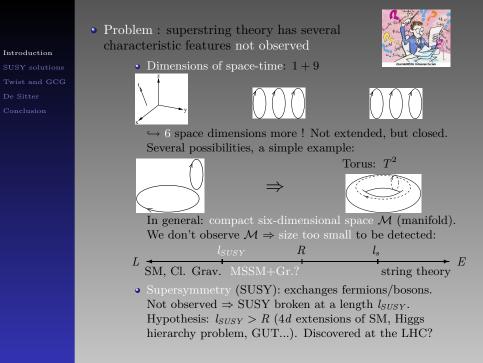


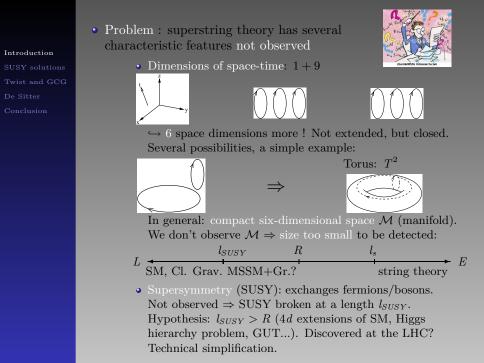


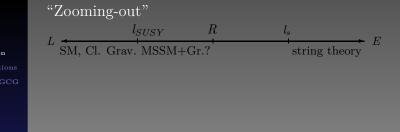


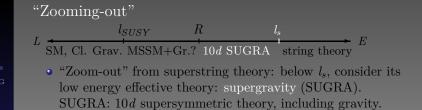












"Zooming-out" l_{SUSY} REL SM, Cl. Grav. MSSM+Gr.? 10d SUGRA string theory • "Zoom-out" from superstring theory: below l_s , consider its low energy effective theory: supergravity (SUGRA). SUGRA: 10d supersymmetric theory, including gravity.

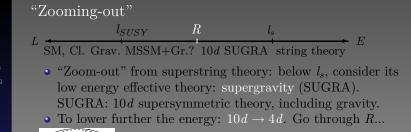
• To lower further the energy: $10d \rightarrow 4d$. Go through R_{\dots}

Introduction





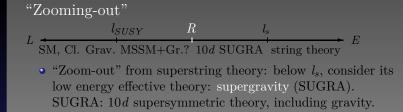
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Technical procedure: Kaluza-Klein (KK) reduction:

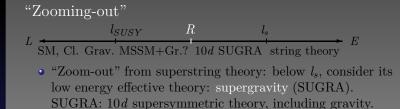


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Technical procedure: Kaluza-Klein (KK) reduction:find a background (a solution to 10d equations of motion, a vacuum of SUGRA)



Conclusion

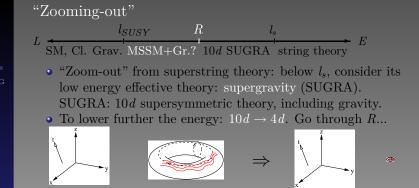
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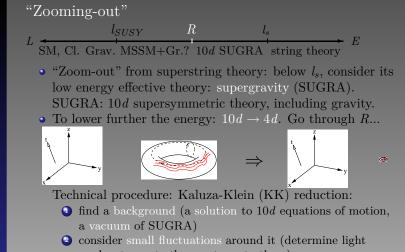
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- find a background (a solution to 10*d* equations of motion, a vacuum of SUGRA)
- consider small fluctuations around it (determine light modes, truncate the spectrum to them)

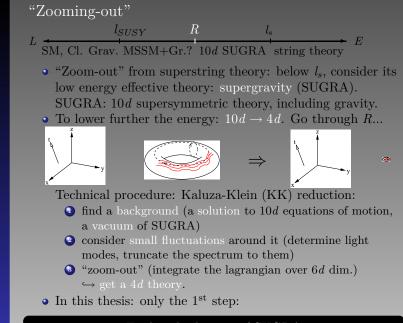


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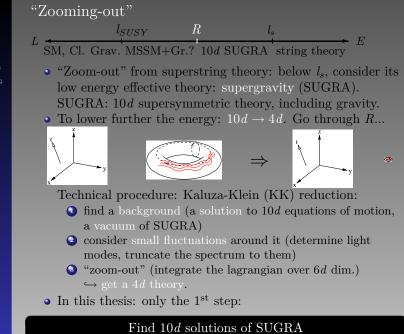
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- "zoom-out" (integrate the lagrangian over 6d dim.) $\hookrightarrow \text{get a } 4d \text{ theory.}$
- In this thesis: only the 1st step:



Find 10d solutions of SUGRA



on 4d + 6d, and preserve some SUSY...

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Type IIA/B SUGRA: $\mathcal{N}_{10d} = 2$ SUSY

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Type IIA/B SUGRA: $\mathcal{N}_{10d} = 2$ SUSY Spectrum:

- bosons of NSNS sector: g_{MN} , ϕ , $B_{(2)}$, $M = 0 \dots 9$, H = dB flux
- bosons of RR sector: C_{p-1} , p even/odd in IIA/B, $F_p \sim dC_{p-1}$ flux
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To get a solution:

- solve equations of motion: Einstein, ϕ , fluxes (F, H).
- solve the Bianchi identities (BI) of the fluxes (sources...).

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Supersymmetric solutions and choice of \mathcal{M}

Preserve SUSY in the vacuum \Rightarrow SUSY conditions.

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Choice of the internal manifold \mathcal{M} CY is Ricci flat.

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Choice of the internal manifold \mathcal{M} CY is Ricci flat.

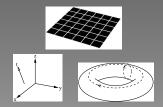
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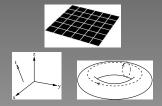


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Introduction SUSY solutions Twist and GCG Choice of the internal manifold \mathcal{M}

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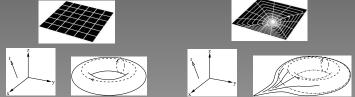
In presence of fluxes: they backreact on \mathcal{M} \hookrightarrow a priori \mathcal{M} not flat anymore... GCY!



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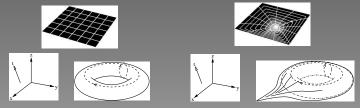
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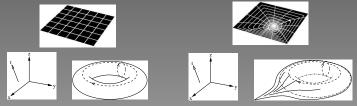


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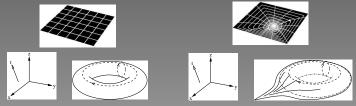
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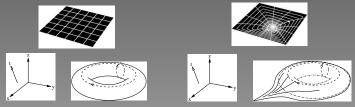
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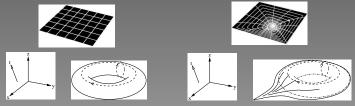
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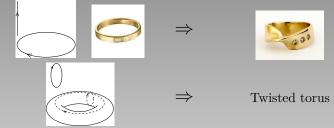
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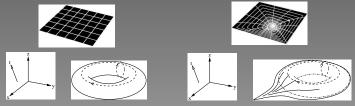
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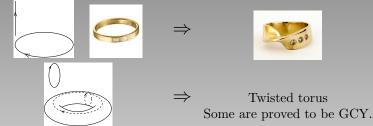
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SUSY solutions of 10d SUGRA

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SUSY solutions of 10d SUGRA with fluxes, on $\mathcal{M} = \text{GCY}$

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• SUSY conditions. SUSY solutions on twisted tori.

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SUSY solutions of 10d SUGRA with fluxes, on $\mathcal{M} = \text{GCY}$

• SUSY conditions. SUSY solutions on twisted tori.

• Twisted tori as solvmanifolds. Twist transformation

 \hookrightarrow can relate and generate solutions. Generalized Complex Geometry (GCG).

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• De Sitter solutions: cosmology.



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The SUSY conditions

• For $\mathbb{R}^{3,1} \times \mathcal{M}$, SUSY conditions:

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The SUSY conditions

• For $\mathbb{R}^{3,1} \times \mathcal{M}$, SUSY conditions:

 $0 = \delta \psi_M$

$$0 = \delta \tilde{\lambda}$$

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The SUSY conditions

• For $\mathbb{R}^{3,1} \times \mathcal{M}$, SUSY conditions: $0 = \delta \psi_M = D_M \epsilon + \frac{1}{4} H_M \mathcal{P} \epsilon + \frac{1}{16} e^{\phi} \sum_n \mathcal{V}_{2n} \gamma_M \mathcal{P}_n \epsilon$ $0 = \delta \tilde{\lambda} = \left(\partial \!\!\!/ \phi + \frac{1}{2} \mathcal{H} \mathcal{P} \right) \epsilon + \frac{1}{8} e^{\phi} \sum_n (-1)^{2n} (5-2n) \mathcal{V}_{2n} \mathcal{P}_n \epsilon$ 10d SUSY parameters: $\epsilon = (\epsilon^1, \epsilon^2)^n$.

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The SUSY conditions

• For $\mathbb{R}^{3,1} \times \mathcal{M}$, SUSY conditions: CY condition: $D_m \eta = 0$. $0 = \delta \psi_M = D_M \epsilon$

$$0 = \delta \tilde{\lambda} = \left(\partial \phi \right) \epsilon$$

10d SUSY parameters: $\epsilon = (\epsilon^1, \epsilon^2)$. Fluxes in the SUSY conditions

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For ℝ^{3,1} × M, SUSY conditions: CY condition: D_mη = 0.
0 = δψ_M = D_Mϵ + ¹/₄H_MPϵ + ¹/₁₆e^φ ∑_n 𝑘_{2n}γ_MP_nϵ
0 = δλ̃ = (𝑘φ + ¹/₂𝑘P) ϵ + ¹/₈e^φ ∑_n(-1)²ⁿ(5 - 2n) 𝑘_{2n}P_nϵ
10d SUSY parameters: ϵ = (ϵ¹, ϵ²)ⁿ.
Fluxes in the SUSY conditions ⇒ GCG rewriting.
Decompose according to SO(1, 3) × SO(6): ϵ^{i=1,2} → η^{i=1,2}.
⇒ SUSY conditions on M.

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SUSY conditions rewritten with polyforms, $\mathcal{M} = GCY$.

SUSY solutions

• Explicit flux solutions on non-CY?

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• Explicit flux solutions on non-CY? Via T-duality...

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• Explicit flux solutions on non-CY? Via T-duality... IIB solution: warped T^6 + O3-plane + fluxes (H, F_3, F_5)

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• Explicit flux solutions on non-CY? Via T-duality... IIB solution: warped T^6 + O3-plane + fluxes (H, F_3, F_5) Two T-dualities along $T^2 \rightarrow$ flux solution on twisted torus. $T^2 \rightarrow \mathcal{M}$

 T^4

 $T^6 = T^2 \times T^4 \xrightarrow{T-d.}$

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$$T^6 = T^2 \times T^4 \quad \frac{T-d}{d}$$

• SUSY conditions + BI \Rightarrow e.o.m. T^4 SUSY conditions are more tractable in terms of GCG.

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SUSY conditions + BI ⇒ e.o.m. T⁴
 SUSY conditions are more tractable in terms of GCG.
 ⇒ systematic resolution method to get solutions.

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 → systematic resolution method to get solutions.
- \Rightarrow a whole list of solutions: ex. in IIB with O5:

	Algebras	O5	
		SU(3)	$\perp SU(2)$
$n \ 3.14$	(0, 0, 0, 12, 23, 14 - 35)	45 + 26	
n 4.4	(0, 0, 0, 0, 12, 14 + 23)	56	56
n 4.5	(0, 0, 0, 0, 12, 34)	56	56
n 4.6	(0, 0, 0, 0, 12, 13)	56	56
n 4.7	(0, 0, 0, 0, 13 + 42, 14 + 23)	56	56
n 5.1	(0, 0, 0, 0, 0, 0, 12 + 34)	56	56
s 2.5	(25, -15, r45, -r35, 0, 0)	13 + 24	13 + 24

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- Can all solutions be related a transformation? (no isolated solution)
 - \hookrightarrow Twist transf.: relate/generate solutions on twisted tori.

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Twisted tori: nil- and solvmanifolds

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Twisted tori: nil- and solvmanifolds

• Built out of Lie groups G nilpotent or solvable.

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Twisted tori: nil- and solvmanifolds

Built out of Lie groups G nilpotent or solvable.
 Nilmanifolds ⊂ solvmanifolds (nilpotent ⊂ solvable).

Twist transformation

Twisted tori: nil- and solvmanifolds

Built out of Lie groups G nilpotent or solvable.
 Nilmanifolds ⊂ solvmanifolds (nilpotent ⊂ solvable).
 All nilmanifolds are GCY ⇒ interesting candidates for M.

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Twisted tori: nil- and solvmanifolds

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 General nilmanifold :

$$\begin{pmatrix} \mathcal{F}^p & \hookrightarrow & \mathcal{M}^p \\ & & \downarrow \\ & & \vdots \\ \mathcal{F}^1 & \hookrightarrow & \mathcal{M}^1 \\ & & & \downarrow \\ & & & \mathcal{B}^1 \end{pmatrix} = N/\Gamma_N$$

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Twisted tori: nil- and solvmanifolds

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• The algebra gives the Maurer-Cartan (MC) equation: $[E_i, E_j] = f^k_{ij} E_k \iff de^k = -\sum_{i < j} f^k_{ij} e^i \wedge e^j .$ $E_i \in \mathfrak{g}: \text{ vector}, e^i \in \mathfrak{g}^*: \text{ dual 1-form}, f^k_{ij}: \text{ struct. constants.}$

Twisted tori: nil- and solvmanifolds

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 [E_i, E_j] = f^k_{ij} E_k ⇔ de^k = -∑_{i < j} f^k_{ij} eⁱ ∧ e^j.
 E_i ∈ g: vector, eⁱ ∈ g^{*}: dual 1-form, f^k_{ij}: struct. constants.
 Out of the MC equation, one can read the topology.
 Topological properties encoded in the MC 1-forms.

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Topological properties encoded in the MC 1-forms.
→ twist transformation uses this idea.

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To reproduce a change of topology, we transform the 1-forms. Here: obtain 1-forms of the solvmanifold out of those of T^6 :

$$A \quad \left(\begin{array}{c} \mathrm{d}x^1\\ \vdots\\ \mathrm{d}x^6 \end{array}\right) = \left(\begin{array}{c} e^1\\ \vdots\\ e^6 \end{array}\right)$$

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A encodes the topology.

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To reproduce a change of topology, we transform the 1-forms. Here: obtain 1-forms of the solvmanifold out of those of T^6 : $A \begin{pmatrix} dx^1 \\ \vdots \end{pmatrix} = \begin{pmatrix} e^1 \\ \vdots \end{pmatrix}.$

$$(ax^{-})$$
 (e^{-})
A encodes the topology. Given the Mostow bundle

$$\begin{pmatrix} \mathcal{F}^p & \hookrightarrow & \mathcal{M}^p \\ & \downarrow \\ & \ddots \\ \mathcal{F}^1 & \hookrightarrow & \mathcal{M}^1 \\ & & \mathcal{B}^1 \end{pmatrix} = N/\Gamma_N \quad \hookrightarrow \quad \mathcal{M} = G/\Gamma$$

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• Transformation relating 1-forms of T^6 to 1-forms of a twisted torus, reproduces the change of topology.

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 ⇒ extend the twist in GCG...

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- Transformation relating 1-forms of T⁶ to 1-forms of a twisted torus, reproduces the change of topology.
 ⇒ extend the twist in GCG...
- GCG considers the fibration:

TM

 $\begin{array}{cccc} T^*M & \hookrightarrow & E \\ & & | \end{array}$

E: the generalized tangent bundle.

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Transformation relating 1-forms of T⁶ to 1-forms of a twisted torus, reproduces the change of topology.
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 $T^*M \hookrightarrow E$

E: the generalized tangent bundle.

Locally: $TM \oplus T^*M$.

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 $T^*M \hookrightarrow E$

 \downarrow E: the generalized tangent bundle. TM

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$$X = v + \xi = \begin{pmatrix} v \\ \xi \end{pmatrix}$$
, $v \in TM$, $\xi \in T^*M$.

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Natural O(d, d) action on $TM \oplus T^*M$.

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Natural O(d, d) action on $TM \oplus T^*M$. One element:

$$\begin{pmatrix} A & 0_d \\ \hline 0_d & A^{-T} \end{pmatrix}$$

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• Spinorial representation of O(d, d): (S)pin(d, d)

 \Rightarrow Majorana-Weyl spinors on $TM \oplus T^*M$

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 ⇒ extend the twist in GCG...
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- Spinorial representation of O(d, d): (S)pin(d, d)
 - $\Rightarrow \text{ Majorana-Weyl spinors on } TM \oplus T^*M: \Phi_{\pm} = \eta_{\pm}^1 \otimes \eta_{\pm}^{2\dagger}.$

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 ⇒ extend the twist in GCG...
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 $T^*M \hookrightarrow E$

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Locally: $TM \oplus T^*M$. Sections: generalized vectors:

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• Spinorial representation of O(d, d): (S)pin(d, d) \Rightarrow Majorana-Weyl spinors on $TM \oplus T^*M$: $\Phi_{\pm} = \eta_{\pm}^1 \otimes \eta_{\pm}^{2\dagger}$. They transform: $\Phi \mapsto \Phi' = O \cdot \Phi$.

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Solutions on torus and on twisted tori.
 Our solutions are given in terms of the polyforms Φ_±.

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 Solutions on torus and on twisted tori. Our solutions are given in terms of the polyforms Φ_±.
 Φ_± can encode a solution (NSNS, RR via SUSY) Introduction SUSY solutions Twist and GCG Twisted tori Twist GCG Solutions De Sitter

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 Solutions on torus and on twisted tori. Our solutions are given in terms of the polyforms Φ_±.
 Φ_± can encode a solution (NSNS, RR via SUSY)
 → a transformation (T-duality, Twist...) could lead to another solution...

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 \hookrightarrow relate solutions with the twist?

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 \hookrightarrow relate solutions with the twist?

• Consider a solution of the SUSY conditions.

$$(\mathbf{d} - H \wedge)(e^{2A - \phi} \Phi_1) = 0 (\mathbf{d} - H \wedge)(e^{A - \phi} \operatorname{Re}(\Phi_2)) = 0 (\mathbf{d} - H \wedge)(e^{3A - \phi} \operatorname{Im}(\Phi_2)) = E$$

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• Consider a solution of the SUSY conditions. Perform a Twist: $\Phi'_{+} = O \cdot \Phi_{\pm} \Rightarrow$ Get a new solution?

$$\begin{aligned} (\mathrm{d}-H\wedge)(e^{2A-\phi}\Phi_1) &= 0 & (\mathrm{d}-H'\wedge)(e^{2A-\phi}\Phi_1') &= 0 \\ (\mathrm{d}-H\wedge)(e^{A-\phi}\operatorname{Re}(\Phi_2)) &= 0 & \Rightarrow & (\mathrm{d}-H'\wedge)(e^{A-\phi}\operatorname{Re}(\Phi_2')) &= 0 \\ (\mathrm{d}-H\wedge)(e^{3A-\phi}\operatorname{Im}(\Phi_2)) &= R & (\mathrm{d}-H'\wedge)(e^{3A-\phi}\operatorname{Im}(\Phi_2')) &= R' \end{aligned}$$

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 Solutions on torus and on twisted tori. Our solutions are given in terms of the polyforms Φ_±.
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Expand in terms of $\Phi_{1,2}, R, O \Rightarrow$ constraints on the twist with respect to the first solution.

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Conclusion

 Solutions on torus and on twisted tori. Our solutions are given in terms of the polyforms Φ_±.
 Φ_± can encode a solution (NSNS, RR via SUSY)
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• Consider a solution of the SUSY conditions. Perform a Twist: $\Phi'_{+} = O \cdot \Phi_{\pm} \Rightarrow$ Get a new solution?

$$\begin{aligned} (\mathbf{d} - H \wedge)(e^{2A - \phi} \Phi_1) &= 0 & (\mathbf{d} - H' \wedge)(e^{2A - \phi} \Phi'_1) &= 0 \\ (\mathbf{d} - H \wedge)(e^{A - \phi} \operatorname{Re}(\Phi_2)) &= 0 & \Rightarrow & (\mathbf{d} - H' \wedge)(e^{A - \phi} \operatorname{Re}(\Phi'_2)) &= 0 \\ (\mathbf{d} - H \wedge)(e^{3A - \phi} \operatorname{Im}(\Phi_2)) &= R & (\mathbf{d} - H' \wedge)(e^{3A - \phi} \operatorname{Im}(\Phi'_2)) &= R' \end{aligned}$$

Expand in terms of $\Phi_{1,2}, R, O \Rightarrow$ constraints on the twist with respect to the first solution. For instance:

$$\mathrm{d}(O)\cdot\Phi_1=0.$$

Examples of constraints and solutions, with SU(3) structure: $\Phi_+ = N_+ e^{i\theta} e^{-iJ}$, $\Phi_- = -N_-i \Omega_3$.

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Examples of constraints and solutions, with SU(3) structure: $\Phi_+ = N_+ e^{i\theta} e^{-iJ}$, $\Phi_- = -N_-i \Omega_3$. • Nilmanifolds $T^2 \hookrightarrow \mathcal{M}$ $T^6 = T^2 \times T^4 \Rightarrow \qquad \downarrow$ T^4

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Examples of constraints and so	lutions, with $SU(3)$ structure:
$\Phi_+ = N_+ e^{i\theta} \ e^{-iJ}$	$, \Phi = -N i \ \Omega_3 \ .$
• Nilmanifolds	$T^2 \hookrightarrow \mathcal{M}$
$T^6 = T^2 \times T^4 \qquad \Rightarrow \qquad$	
	T^4
$(\mathrm{d}z,\mathrm{d}\overline{z})$, $\mathrm{d}x_{\mathcal{B}}^{i=1\dots4}$	$(\mathrm{d}z + \alpha, \mathrm{d}\overline{z} + \overline{\alpha}) , \mathrm{d}x_{\mathcal{B}}^{i=1\dots4}$

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Twisted to

Twist

GCG

Solutions

De Sitter

Examples of constraints and solutions, with SU(3) structure: $\Phi_{+} = N_{+}e^{i\theta} e^{-iJ}$, $\Phi_{-} = -N_{-}i \Omega_{3}$. • Nilmanifolds $T^{2} \hookrightarrow \mathcal{M}$ $T^{6} = T^{2} \times T^{4} \Rightarrow \qquad \downarrow$ $(\mathrm{d}z, \mathrm{d}\overline{z})$, $\mathrm{d}x_{\mathcal{B}}^{i=1...4}$ $(\mathrm{d}z + \alpha, \mathrm{d}\overline{z} + \overline{\alpha})$, $\mathrm{d}x_{\mathcal{B}}^{i=1...4}$ Constraint on the twist of parameter α : $\mathrm{d}\alpha \wedge J_{\mathcal{B}} = 0$, $\mathrm{d}\alpha \wedge \Omega_{\mathcal{B}} = 0$.

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SUSY solution Twist and GC Twisted tori Twist GCG Solutions

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& (dz, d\overline{z}) \ , \ dx_{\mathcal{B}}^{i=1...4} & (dz + \alpha, d\overline{z} + \overline{\alpha}) \ , \ dx_{\mathcal{B}}^{i=1...4} \\
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Constraints can be satisfied on all these $\mathcal{M} \Rightarrow$ solutions!

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$\Phi_+ = N_+ e^{i\theta} \ e^{-iJ}$	$, \Phi = -N i \ \Omega_i$	3 •
• Nilmanifolds	$T^2 \hookrightarrow$	\mathcal{M}
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		T^4
$(\mathrm{d}z,\mathrm{d}\overline{z}) \;,\; \mathrm{d}x^{i=1\dots 4}_{\mathcal{B}}$	$(\mathrm{d}z + \alpha, \mathrm{d}\overline{z} + \overline{\alpha})$,	$\mathrm{d}x_{\mathcal{B}}^{i=1\dots4}$
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Among the 34 nilmanifolds, 5 have this topology. $d\alpha$ is the curvature, precisely defined, related to f^{k}_{ij} . Constraints can be satisfied on all these $\mathcal{M} \Rightarrow$ solutions!

	Algebras	O5	
		SU(3)	$\perp SU(2)$
n 3.14	(0, 0, 0, 12, 23, 14 - 35)	45 + 26	
n 4.4	(0, 0, 0, 0, 12, 14 + 23)	56	56
n 4.5	(0, 0, 0, 0, 12, 34)	56	56
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n 4.7	(0, 0, 0, 0, 13 + 42, 14 + 23)	56	56
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• Solvmanifolds (no T^6 T-dual)

 $s \ 2.5$

Solutions

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Solutions

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C

$$\begin{array}{l} s \ 2.5 \qquad \Rightarrow \qquad \mathfrak{g}_{5.17}^{p,-p,r} \approx s \ 2.5 + p \ \mathfrak{g}_{5.7}^{1,-1,-1} \\ \mathrm{d}J = 0 \\ (\mathrm{Im}\,\Omega_3) = 0 \end{array}$$

SUSY solution

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$$\begin{array}{ll} s \ 2.5 & \Rightarrow & \mathfrak{g}_{5.17}^{p,-p,r} \approx s \ 2.5 + p \ \mathfrak{g}_{5.7}^{1,-1,-1} \\ \mathrm{d}J = 0 & & \mathrm{d}J' = p(\lambda-1) \ \dots \ \mathrm{forms} \\ \mathrm{d}(\mathrm{Im}\,\Omega_3) = 0 & & \mathrm{d}(\mathrm{Im}\,\Omega_3') = p(\lambda-1) \ \dots \ \mathrm{forms} \end{array}$$

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 $\begin{array}{rcl} s \; 2.5 & \Rightarrow & \mathfrak{g}_{5.17}^{p,-p,r} \approx s \; 2.5 + p \; \mathfrak{g}_{5.7}^{1,-1,-1} \\ \mathrm{d}J = 0 & \mathrm{d}J' = p(\lambda-1) \; \dots \; \mathrm{forms} \\ \mathrm{d}(\mathrm{Im}\,\Omega_3) = 0 & \mathrm{d}(\mathrm{Im}\,\Omega_3') = p(\lambda-1) \; \dots \; \mathrm{forms} \\ \mathrm{New \; SUSY \; solution \; on \;} \mathfrak{g}_{5.17}^{p,-p,r} \; \mathrm{for} \; \lambda = 1 \; . \end{array}$

Finding de Sitter solutions

4d =de Sitter, cosmological interest.

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Solutions

Finding de Sitter solutions

4d =de Sitter, cosmological interest. Get solutions: difficult!

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Finding de Sitter solutions

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Finding de Sitter solutions

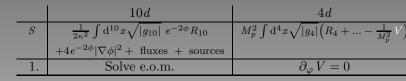
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	10d	4d
S	$\frac{1}{2\kappa^2} \int \mathrm{d}^{10} x \sqrt{ g_{10} } \ e^{-2\phi} R_{10}$	$M_p^2 \int \mathrm{d}^4 x \sqrt{ g_4 } \left(R_4 + \dots - \frac{1}{M_p^2} V \right)$
	$+4e^{-2\phi} \nabla\phi ^2 + \text{ fluxes } + \text{ sources}$	۲
1.	Solve e.o.m.	$\partial_{\varphi} V = 0$

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Finding de Sitter solutions

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10d: without SUSY, technically difficult!
 4d: coupled equations ⇒ numerics...

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1.	Solve e.o.m.	$\partial_{\varphi} V = 0$
2.	$\Lambda = \frac{1}{4}R_4 > 0$	$\Lambda = \frac{1}{2M_p^2} V _0 > 0$

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Finding de Sitter solutions

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- Difficult! Up to date: no stable dS solution with classical 10d SUGRA ingredients.

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De Sittei

Solution

Sources

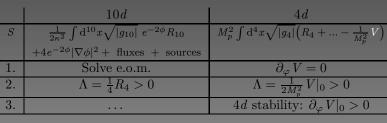
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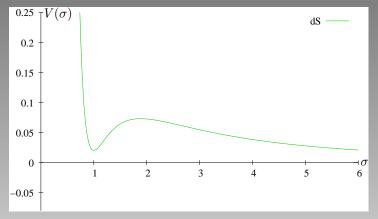
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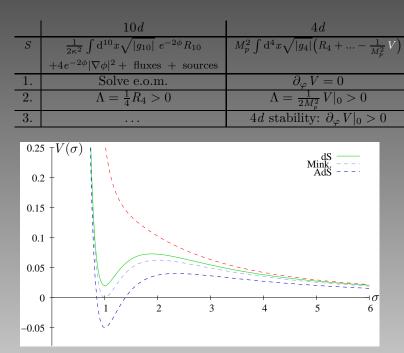




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Several no-go theorems and ways of circumventing them:

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Conclusion

Several no-go theorems and ways of circumventing them:
need O-planes (negatively charged RR sources)
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Several no-go theorems and ways of circumventing them:

need O-planes (negatively charged RR sources)
 ⇒ we take O6/D6 in IIA.

Intersecting sources \Rightarrow smeared sources and constant dilaton $e^{\phi} = g_s$.

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 F_0 alone to balance H_{\cdots} More RR fluxes does not help. \hookrightarrow classical 10*d* SUGRA dS vacuum is difficult! Additional ingredients: KK monopoles and Wilson lines, non-geometric fluxes, α' corrections...

• Proposal: ansatz for SUSY breaking sources. Non-SUSY vacua.

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• Go further: replace Φ_- with X_- in the SUSY conditions. \hookrightarrow first order formalism...

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Einstein equations easier to solve, and new term in R_4 : $R_4 = \frac{2}{3} \left(\frac{g_s}{2} (T_0 - T) + g_s^2 |F_0|^2 - |H|^2 \right)$

 $T = g^{MN} T_{MN}, T_0$ SUSY trace.

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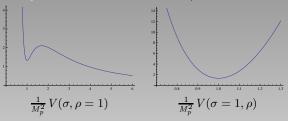
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4d stability: in dilaton σ and volume ρ :



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 SUSY 10d solutions of SUGRA, on 4d Minkowski and M = solvmanifold. Twist transformation: relates and generates such solutions, local O(d, d) transformation in GCG.
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• Understand the twist transformation... Better justification for sources ansatz. Calibration, stability? 1^{st} order formalism.

• Heterotic string: twist transformation and GCG there. Dualities relating flux vacua of het. to those of type II.

• Non-geometry.

• KK reduction: effective actions, model building.